



Brazilian Synchrotron  
Light Laboratory



# Scientific Computing @ Sirius / LNLS

Yuri Rossi Tonin, M. Sc.  
Scientific Computing Specialist  
on behalf of the Scientific Computing group



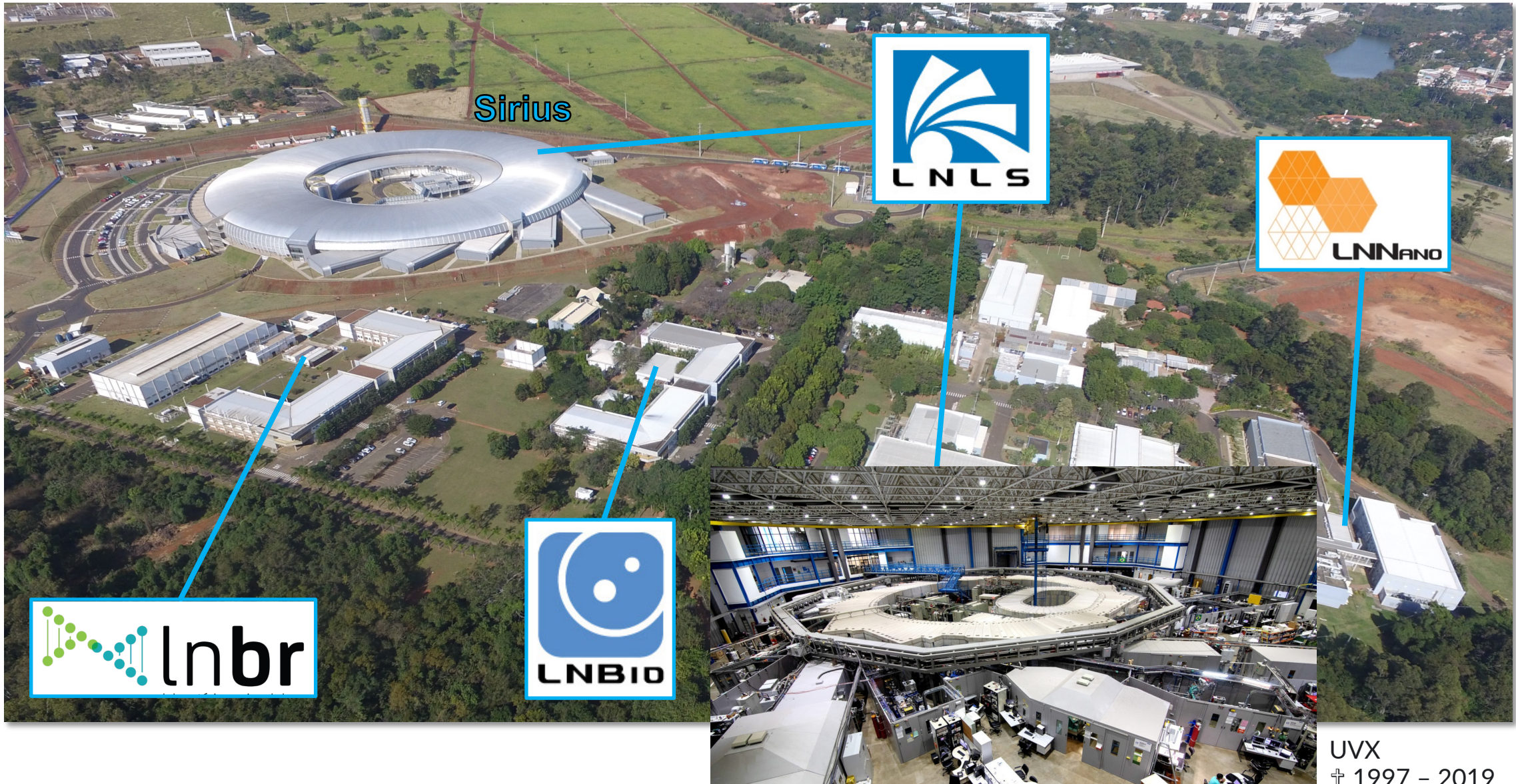


# Outline

- SIRIUS, the new lightsource
- The scientific computing team
- Computing Infrastructure
- Detectors
- Processing pipeline
- Beamline results

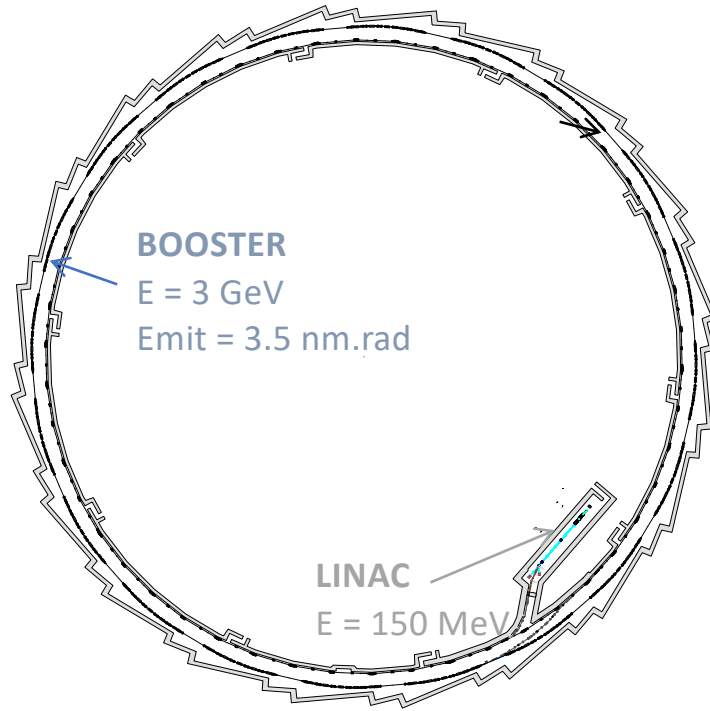








# Sirius Overview



## Storage Ring design parameters

Beam energy	<b>3.0 GeV</b>
Circumference	518 m
Lattice	20 x 5BA
Current, top up	350 mA ( <b>100 mA</b> )
Bunch length	8 ps
Energy spread	0.09 %
RF frequency	500 MHz
Hor. emittance (bare → ids)	<b>250 → 150 pm.rad</b>
Vert. emittance	<b>2.5 → 1.5 pm.rad</b>
Straight section low $\beta_x/\beta_y$	<b>1.5 m / 1.4 m</b>

First beam: Dec 2019

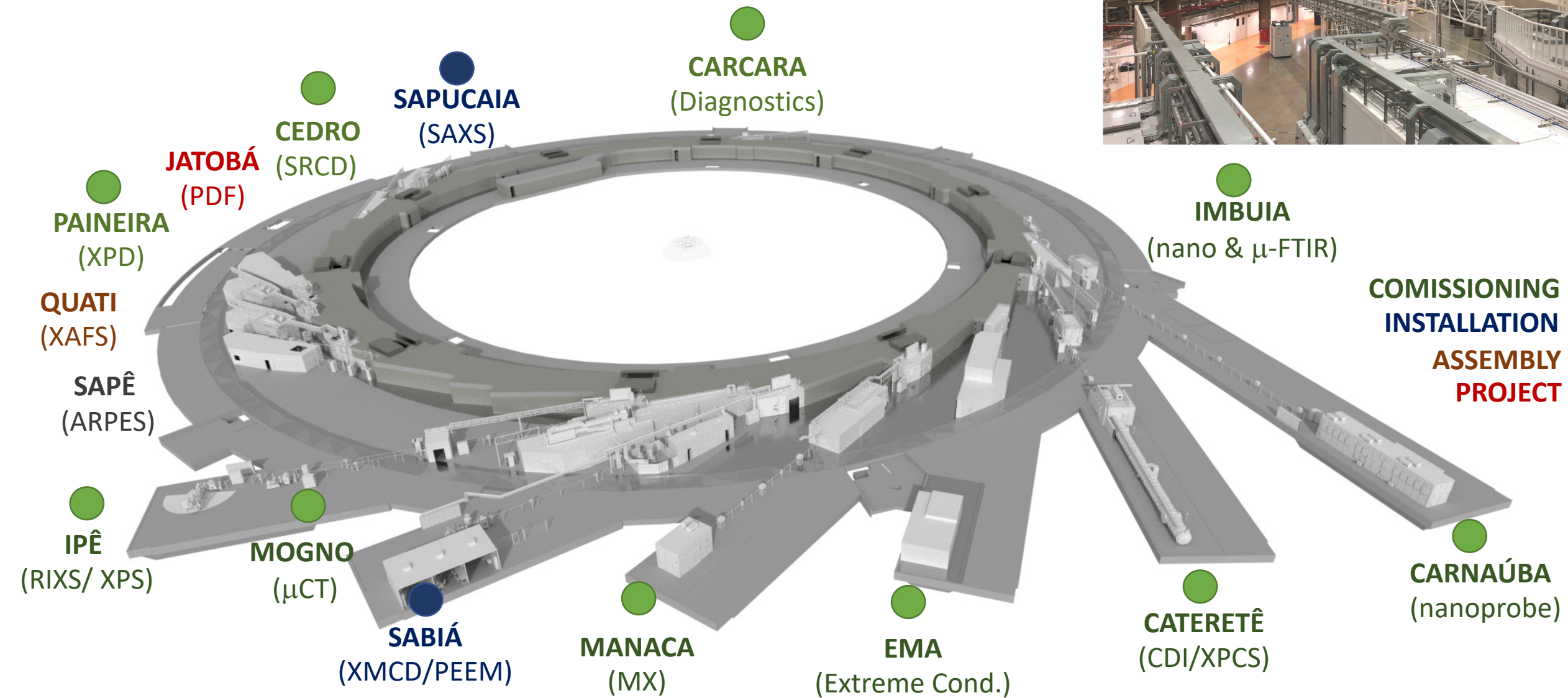


First external users: Sep 2020





# Phase 1A & 1B Beamlines





# “How many beamline does Sirius synchrotron has?”



O Sirius tem 13 linhas de luz em operação atualmente, cada uma projetada para atender a uma área específica de pesquisa. Os nomes das linhas de luz são os seguintes:

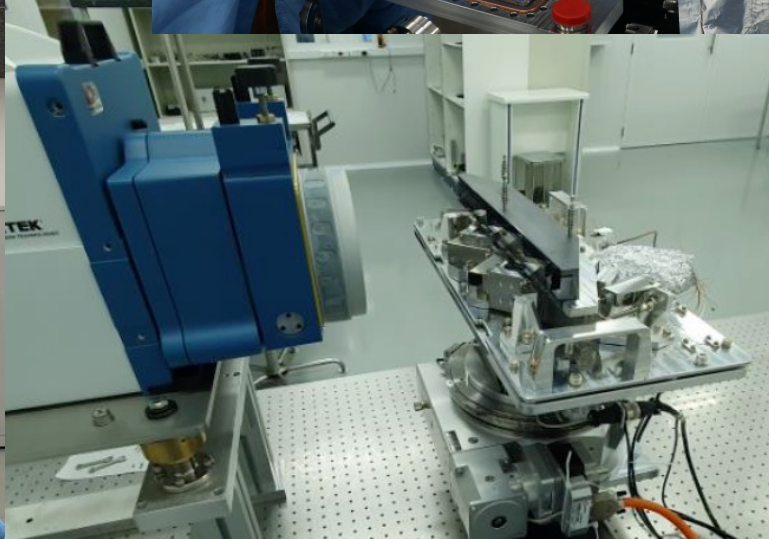
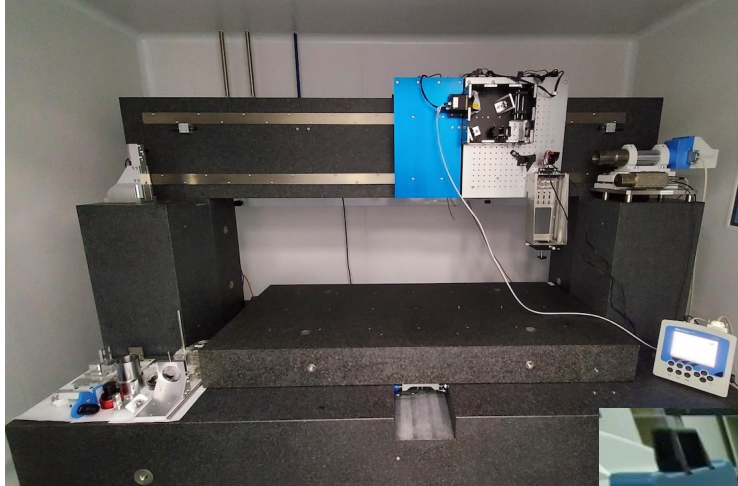
1. Manacá
2. Ipê
3. Abacate
4. Jequitibá
5. Cajuí
6. Uva
7. Graviola
8. Açaí
9. Pitanga
10. Sirius MX
11. Macaúba
12. Cateretê
13. Caracará





# 2019-21 : X-Ray Optics Lab

Long-trace profiler



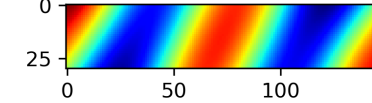
Fizeau interferometer



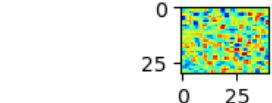
- Self-calibrating stitching interferometry

$$\begin{bmatrix} \mathbf{G} & \mathbf{D} \end{bmatrix} \begin{bmatrix} \mathbf{t}^T \\ \mathbf{r}^T \end{bmatrix} - \mathbf{d}^T \rightarrow \min,$$

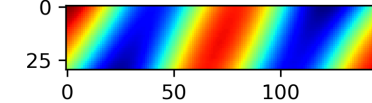
Original  
PV = 2.50e-09 RMS = 7.02e-10



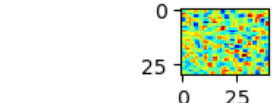
Lens  
PV = 8.94e-11 RMS = 1.57e-11



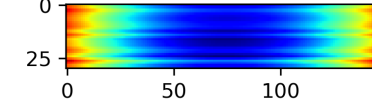
Stitched  
PV = 2.47e-09 RMS = 7.01e-10



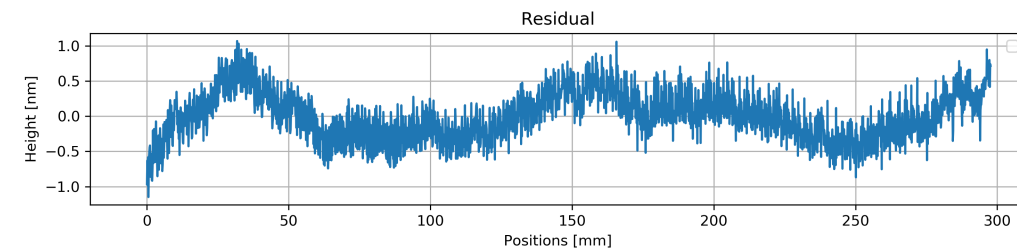
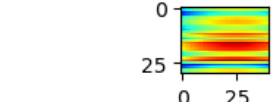
Reconstruction  
PV = 8.97e-11 RMS = 1.54e-11



Difference  
PV = 5.20e-11 RMS = 1.19e-11



Difference  
PV = 1.67e-11 RMS = 3.12e-12





# 21-Present: Scientific Computing

The team:

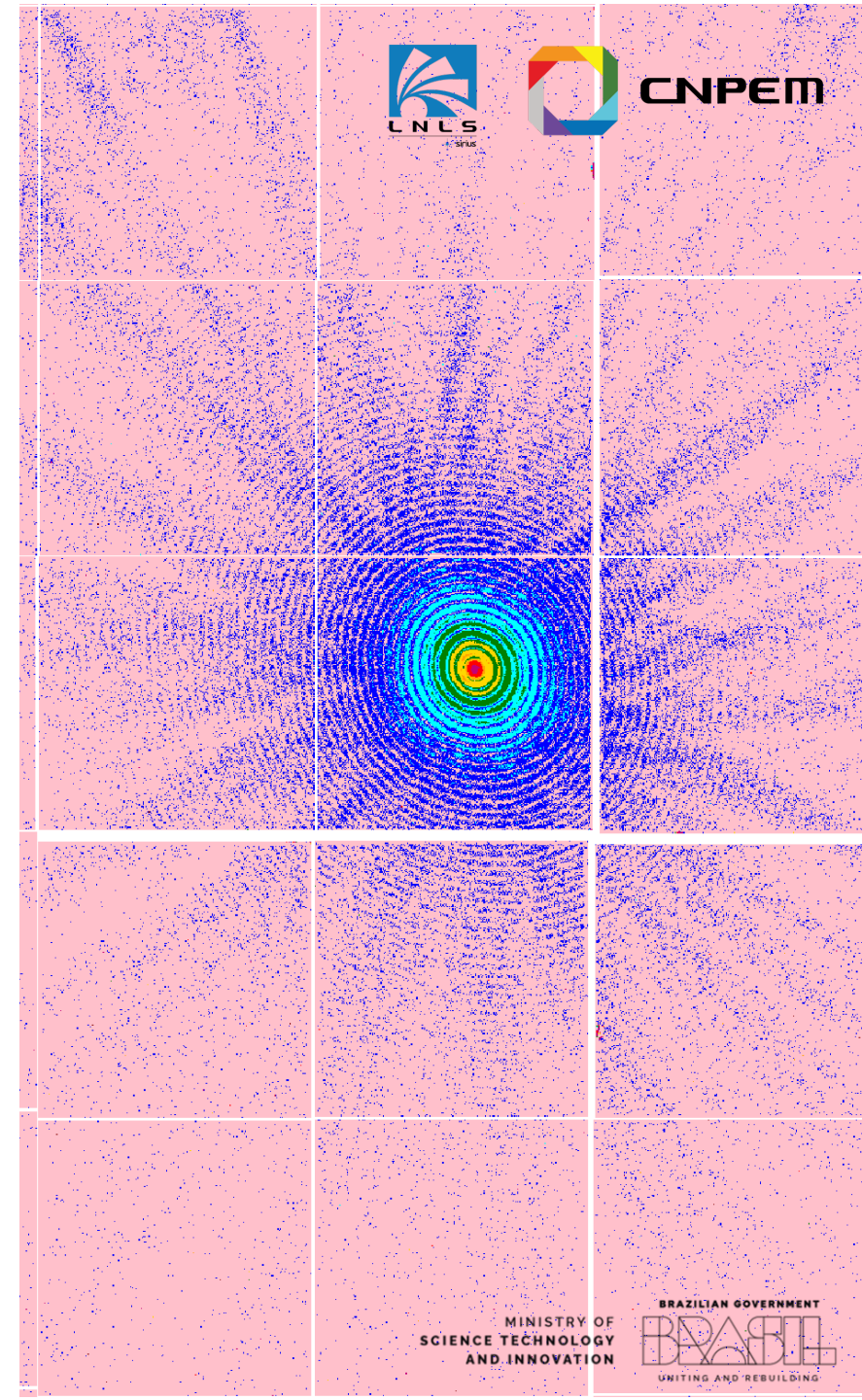


(A) Ricardo Grangeiro / (B) João F. Gondim / (C) Daniel Tavares / (D) Eduardo Miqueles

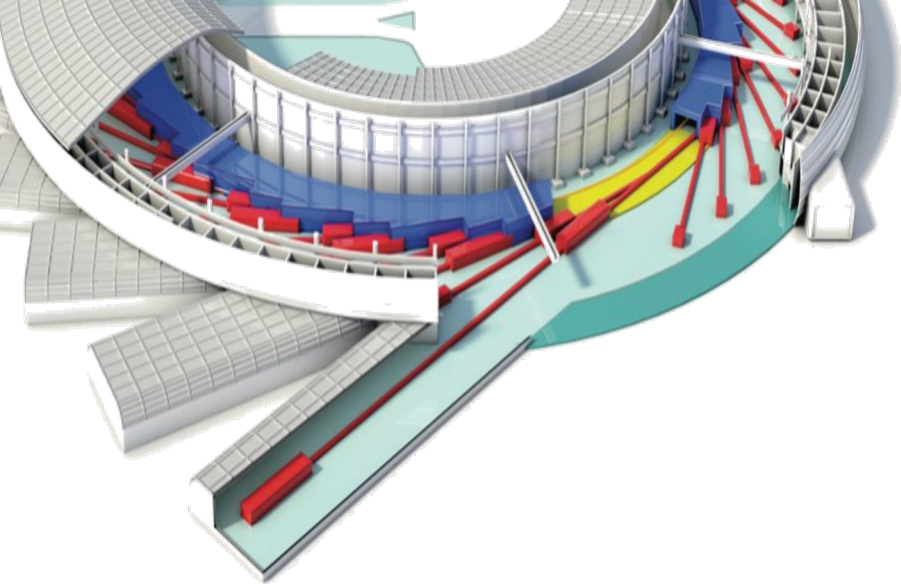
(E) Yuri R. Tonin / (F) Paola C. Ferraz / (G) Julia Carvalho / (H) Gabriel Borin

(I) Larissa Moreno / (J) Alice Kageyama / (K) Larissa Rosa / (L) Camila Lages / (M) Otávio Paiano

• MOGNO / Petrobras: (A), (B), (H), (M)







## Main activities

- *Detector corrections*
  - *Plane-wave CDI*
  - *Ptychography*
  - *Tomography*
  - *Diffraction*
  - *ARPES*
  - *Jupyter interfaces for analysis*
  - *Overall mathematical modelling*
  - *Beamline and user support*
- Make it work (Python)
  - Make it fast (C/CUDA)
  - Well written, well documented
    - Fast to debug
    - Fast to maintain
  - Automatize as much as possible
    - “Single button processing”



# TEPUI: Throughput Enhanced Processing Unit



## Storage

- Storage Unit
- Controllers
- Protocol Gateways

## Network

- Core Switch
- Management Switch

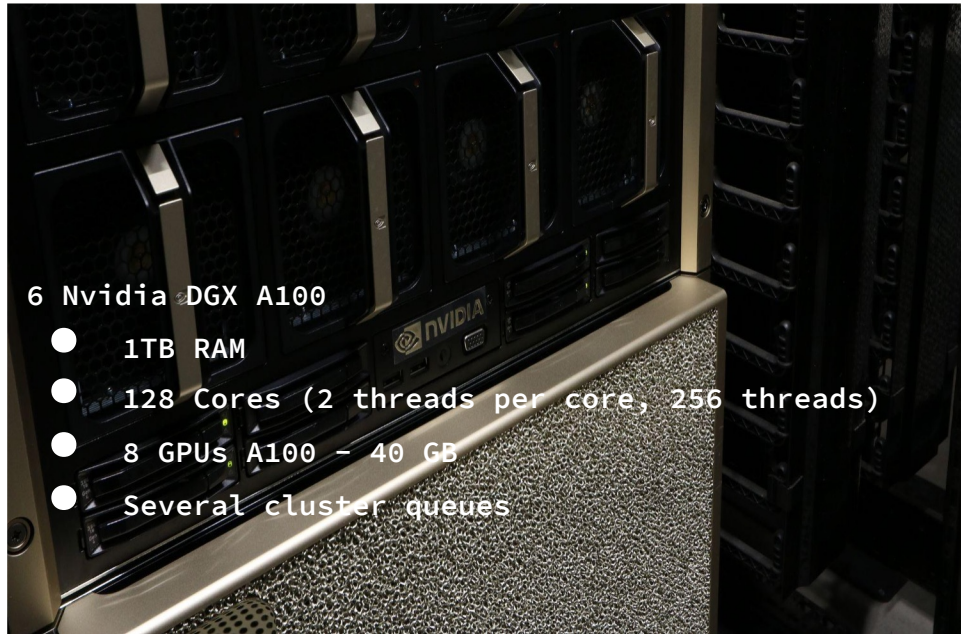
## Servers

- Standalone Servers
- GPU Cluster
- CPU Cluster





# Infrastructure



6 Nvidia DGX A100

- 1TB RAM
- 128 Cores (2 threads per core, 256 threads)
- 8 GPUs A100 – 40 GB
- Several cluster queues

GPU Node



AtoS BullSequana S800

- 6TB RAM
- 224 Cores (2 threads per core, 448 threads)
- 2 cluster queues

CPU Node



HPE Cray ClusterStor E1000

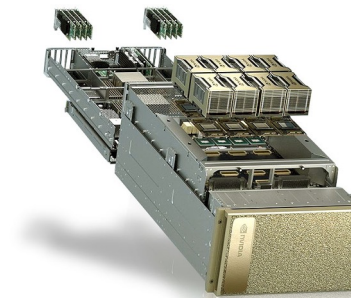
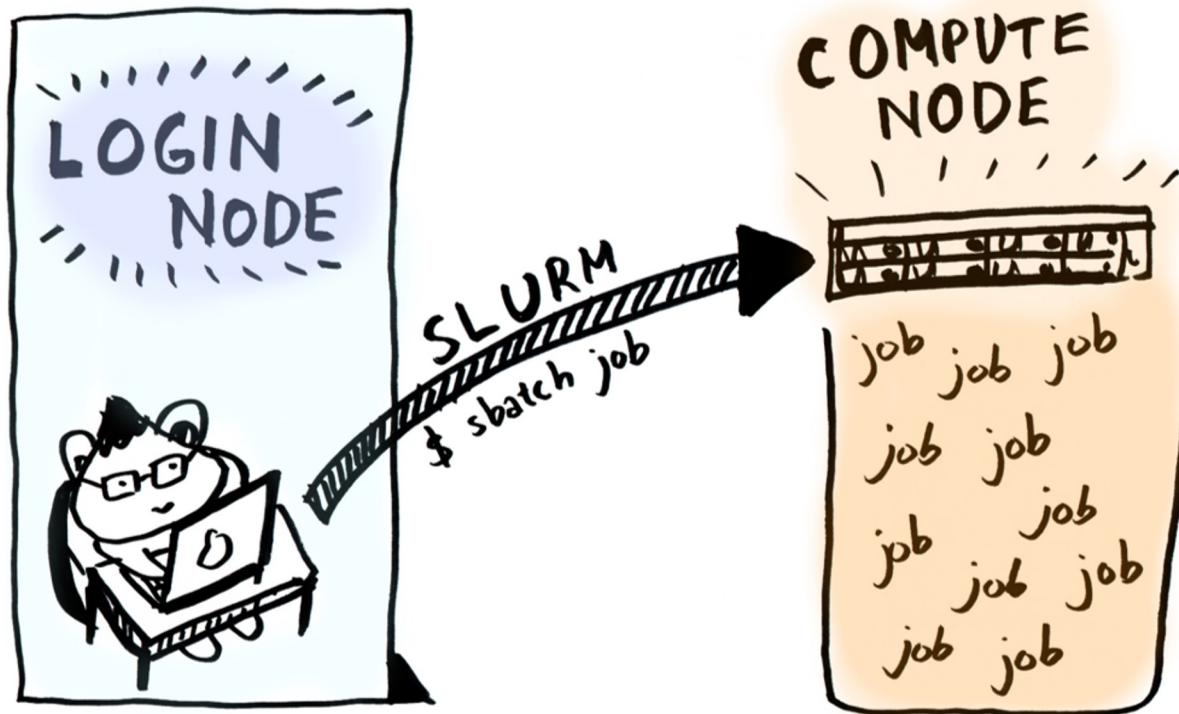
- 4PB
- Lustre Filesystem
- HTTP, FTP, NFS, CIFS gateways

Storage



# Cluster

- Slurm Workload Manager for job scheduling



- Beamline dedicated queues for processing and visualization:

PARTITION	NODELIST	CPUS(A/I/O/T)	FREE_MEM	GRES	GRES_USED	STATE	TIMELIMIT	GroupResources
cpu	enedina	100/348/0/448	6148752	(null)	gpu:0	mixed	5-00:00:00	
imb	enedina	100/348/0/448	6148752	(null)	gpu:0	mixed	3-00:00:00	cpu=32,mem=256G
mgn	mabel	0/256/0/256	887822	gpu:8	gpu:0	idle	3-00:00:00	cpu=160,gpu=5,mem=640G
cnb	mabel	0/256/0/256	887822	gpu:8	gpu:0	idle	3-00:00:00	cpu=96,gpu=3,mem=384G
cat	rosalind	0/256/0/256	730776	gpu:8	gpu:0	idle	3-00:00:00	cpu=160,gpu=5,mem=640G
ema	rosalind	0/256/0/256	730776	gpu:8	gpu:0	idle	3-00:00:00	cpu=32,gpu=1,mem=128G
ipe	rosalind	0/256/0/256	730776	gpu:8	gpu:0	idle	3-00:00:00	cpu=32,gpu=1,mem=128G
pnr	rosalind	0/256/0/256	730776	gpu:8	gpu:0	idle	3-00:00:00	cpu=32,gpu=1,mem=128G
dev-gcc	nise	96/160/0/256	828980	gpu:8	gpu:4	mixed	3-00:00:00	
tepu	harriet	0/256/0/256	993745	gpu:8	gpu:0	idle	3-00:00:00	
petro	aida	32/224/0/256	954461	gpu:8	gpu:2	mixed	3-00:00:00	



# PIMEGA detectors

- Part of Medipix3 collaboration
- Developed in partnership between Detectors group and PiTEC
- <https://www.pitec.co/>



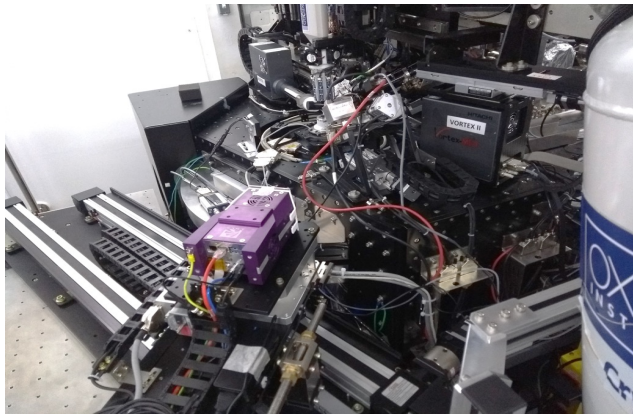
	MOBIPIX 15D	PIMEGA 45D	PIMEGA 135D	PIMEGA 450D	PIMEGA 450DS	PIMEGA 540D
Sensors ( $\mu\text{m}$ material)	300 Si / 1000 CdTe	300 Si	300 Si / 675 Si / 1000 CdTe	675 Si	675 Si	300 Si / 675 Si
Pixels (number / arrangement)	262 kpx / 512 x 512	786 kpx / 512 x 1536	2,4 Mpx / 1536 x 1536	7,9 Mpx / 256 x 30720	7,9 Mpx / 512 x 15360	9,4 Mpx / 3072 x 3072
Pixel size ( $\mu\text{m}^2$ )	55 x 55	55 x 55	55 x 55	55 x 55	55 x 55	55 x 55
Detection area ( $\text{mm}^2$ )	28 x 28	28 x 85	85 x 85	14 x 1692	28 x 850	170 x 170
Active area (%)	99.7	99.6	99	90	90	99
Dynamic range (counts/px/s)	$3 \times 10^5$	$3 \times 10^5$	$3 \times 10^5$	$3 \times 10^5$	$3 \times 10^5$	$3 \times 10^5$
Frame rate @ 12bits (fps)	2000	600	2000	1000	1000	2000
Throughput @ 12bits (Gb/s)	5.9	5.3	52.7	87.9	87.9	211
Readout mode	Continuous or burst	Continuous or burst	Continuous or burst	Continuous or burst	Continuous or burst	Continuous or burst
Vacuum ( $10^{-3}$ mbar)	No	No	Yes	No	No	Yes



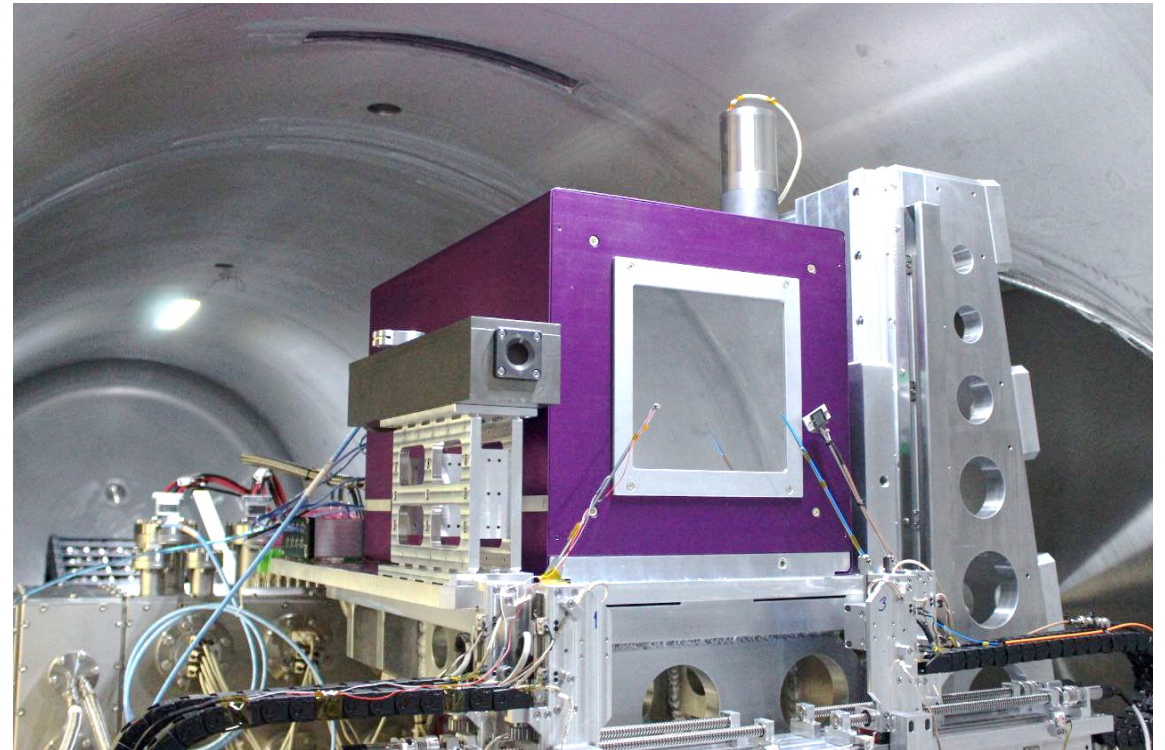
# PIMEGA detectors



Pimega 135D @ Carnaúba

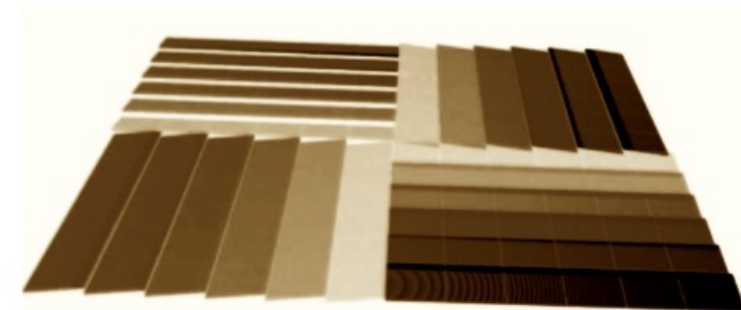


Mobipix @ Carnaúba



Pimega 540D @ Cateretê

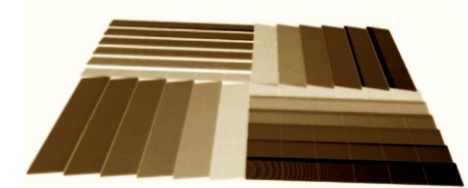
Geometry:



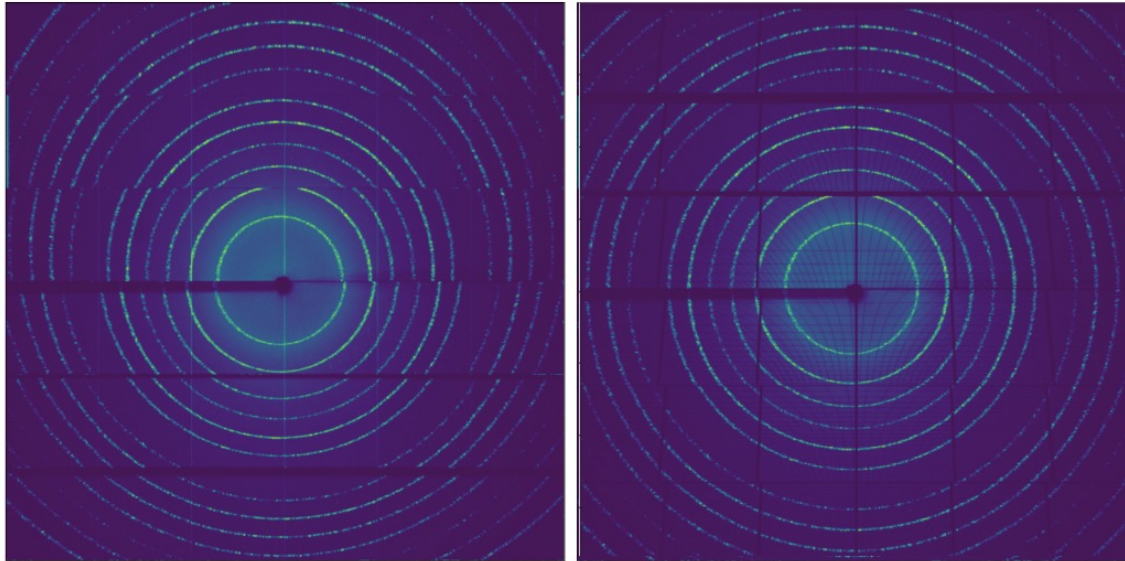


# Restoration

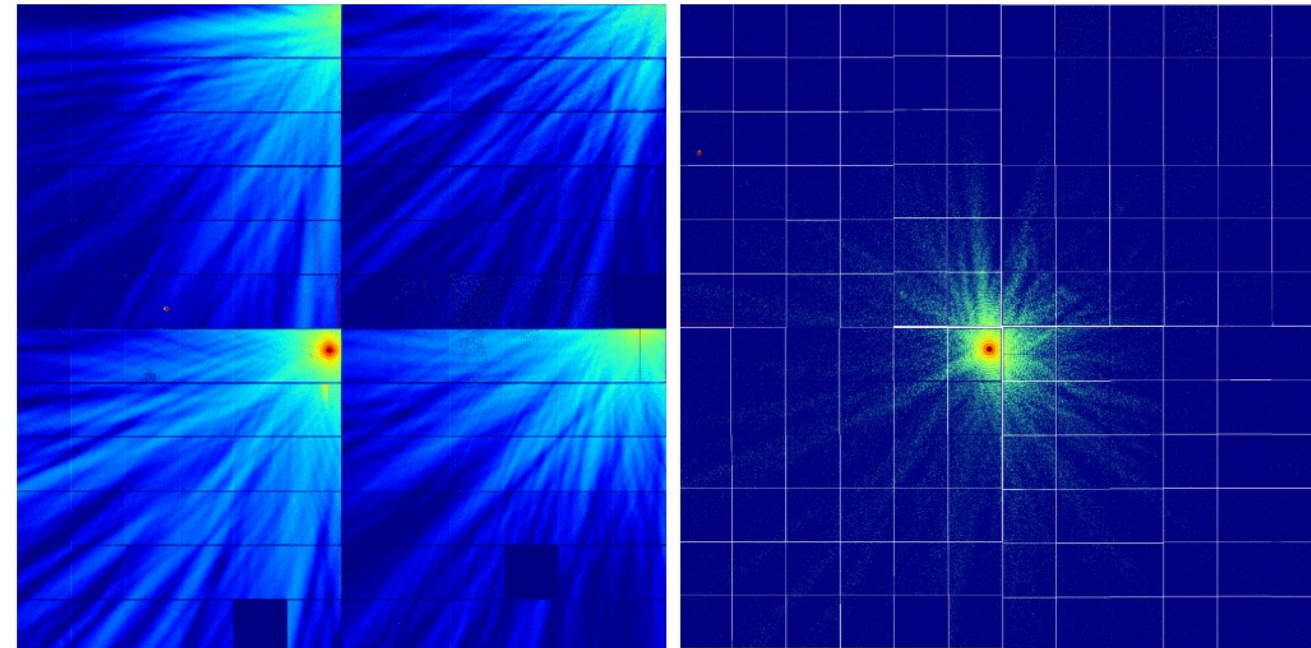
- Tilted chips to minimize gaps
- Geometric corrections necessary to adjust measured images from “tilted” to “virtual plane” chips



Single module, 135D



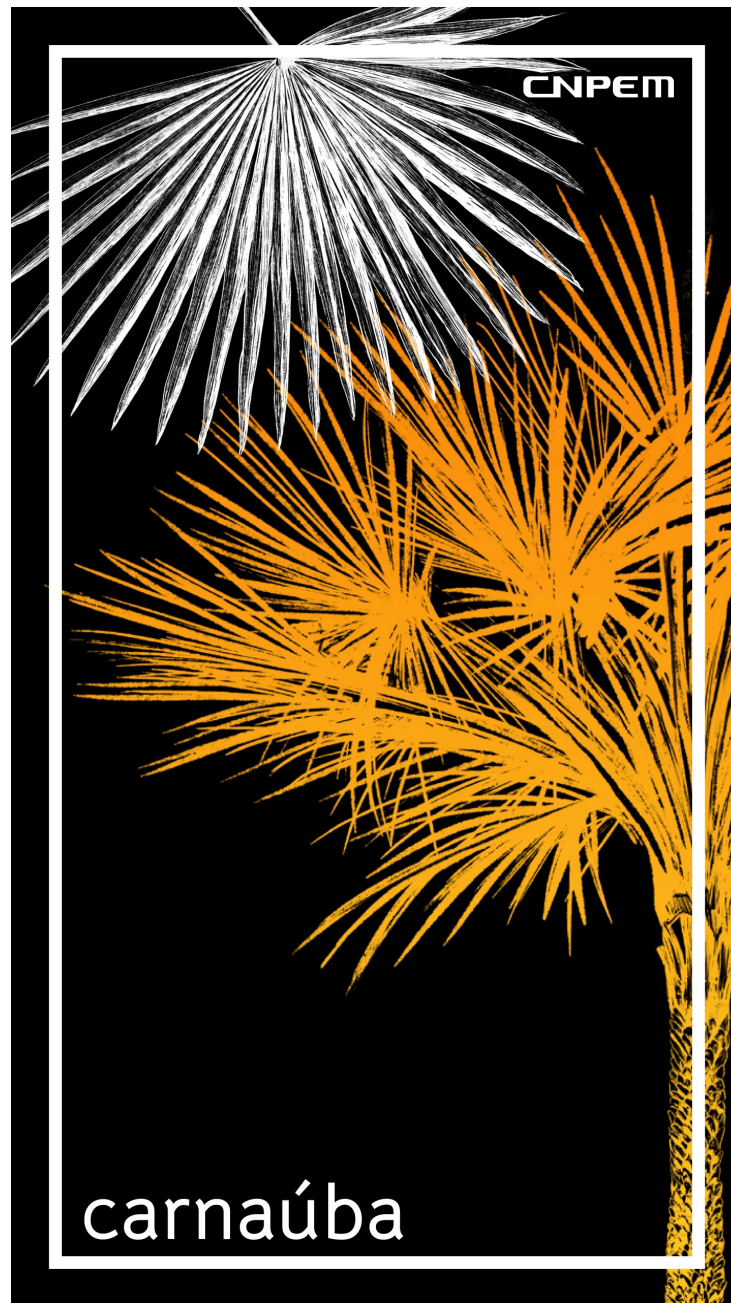
Four modules, 540D



- Restoration time < 1 second per DP (CPU, Python)
- 500 frames: <1 second with GPUs









# CAT RT TÊ

CNPq



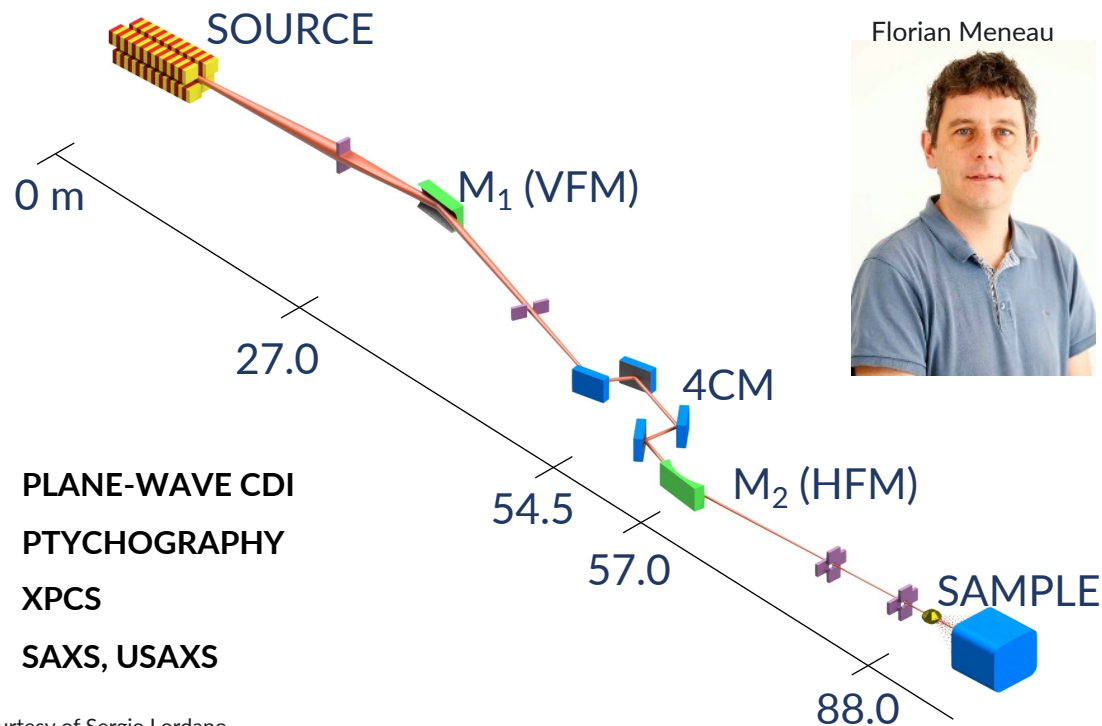
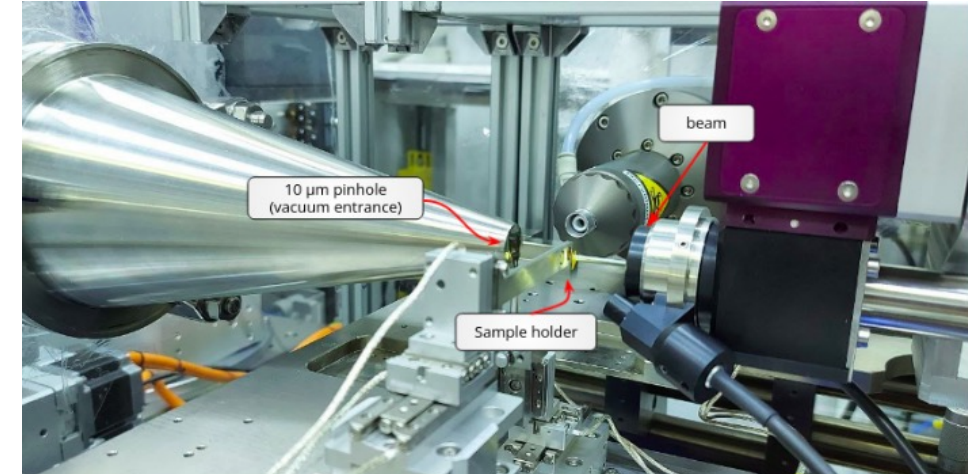
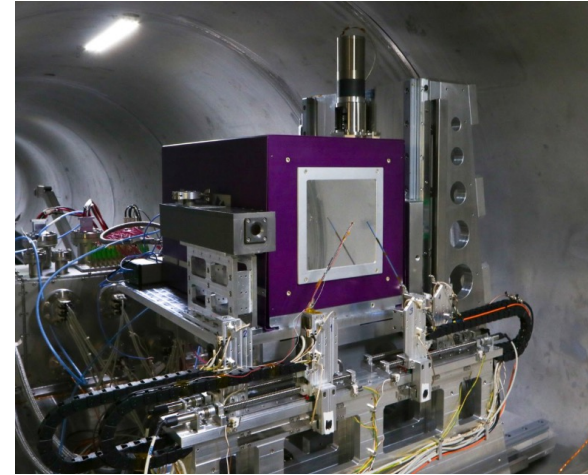
CNPq

## Coherent and Time-resolved X-ray Scattering

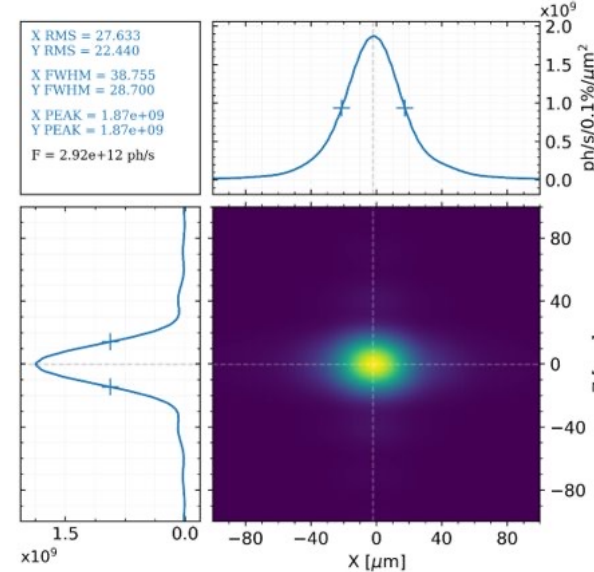




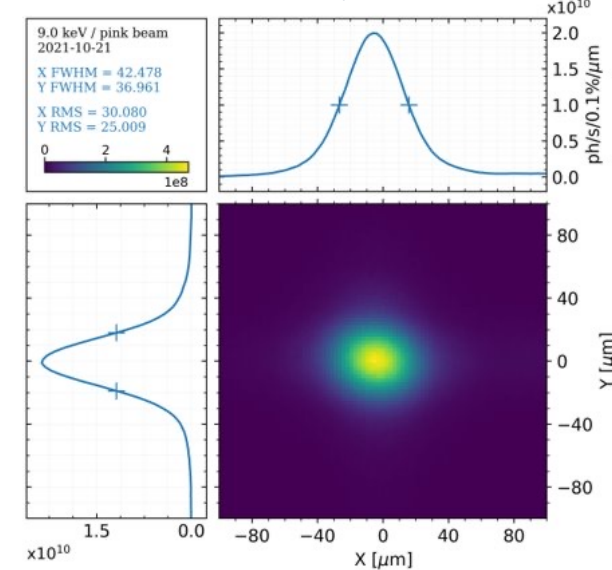
# CATERETÊ beamline



**SIMULATED**  
39 x 29 µm<sup>2</sup>

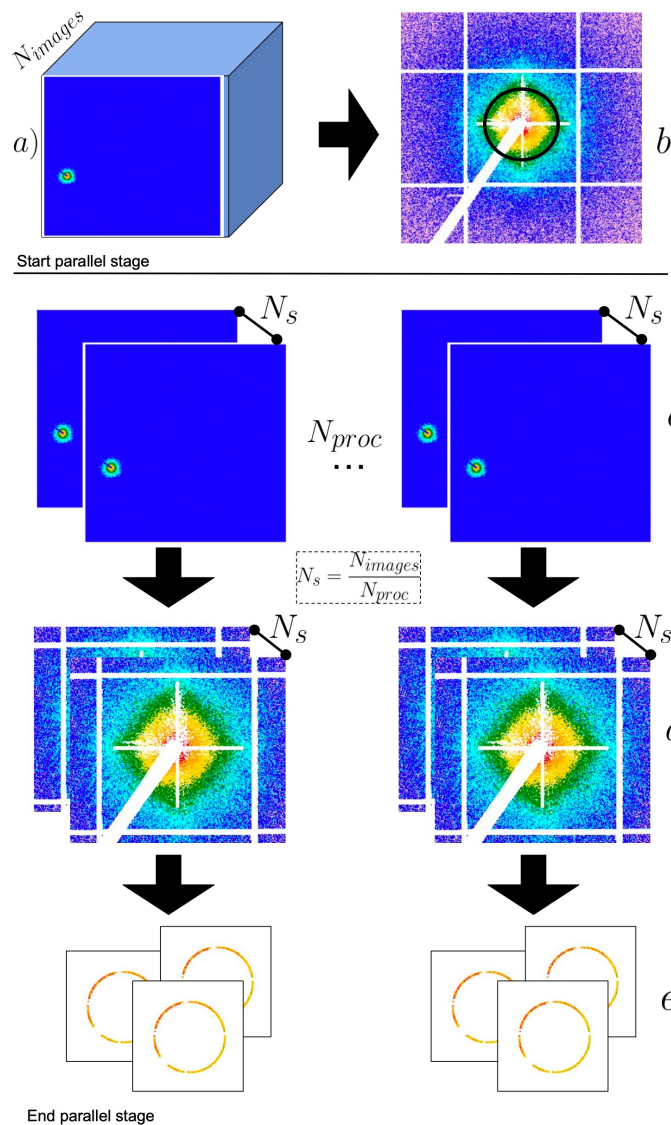


**MEASURED**  
42 x 37 µm<sup>2</sup>

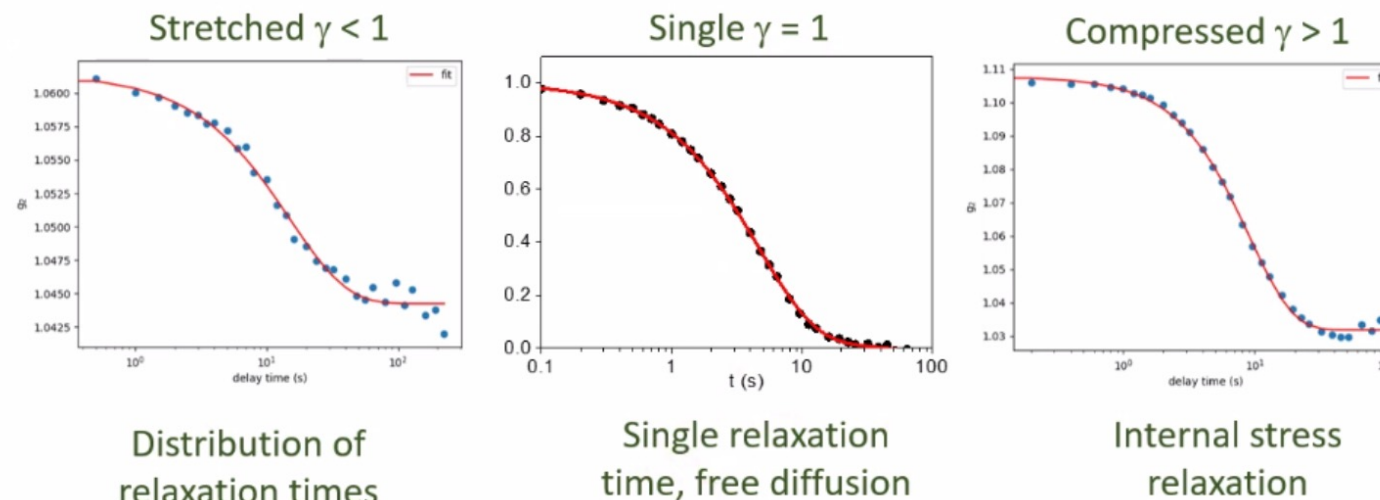




# Cateretê - XPCS



$$g^2(q, t) = \frac{\langle I(q, 0) I(q, t) \rangle}{\langle I(q) \rangle^2} = 1 + \beta \exp(-2(\tau/\tau_r)^\gamma)$$



- XPCS pipeline:
  1. Restoration
  2. Data reduction
  3. Correlation function
- Parallelism in CPU → huge decrease computational time
  - 32 minutes to 18 seconds for 1000 images
- Margin for future improvements using CUDA

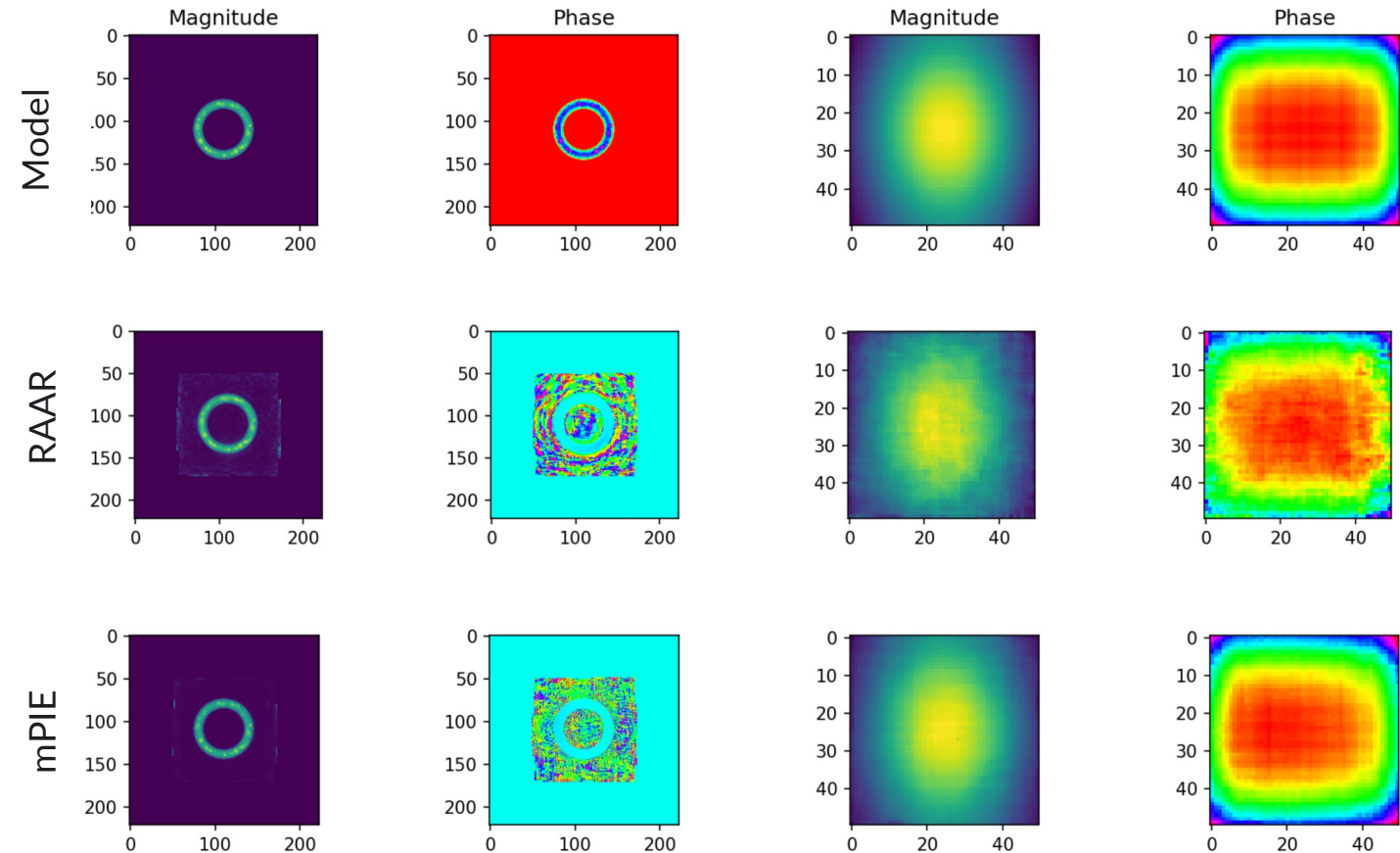


Aline Passos



# Ptychography engines

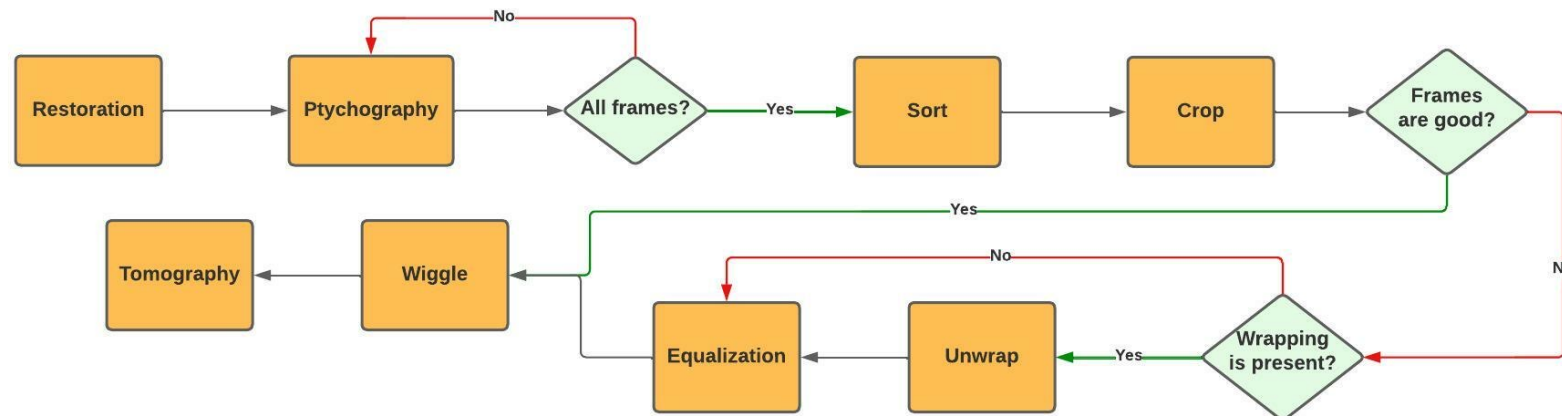
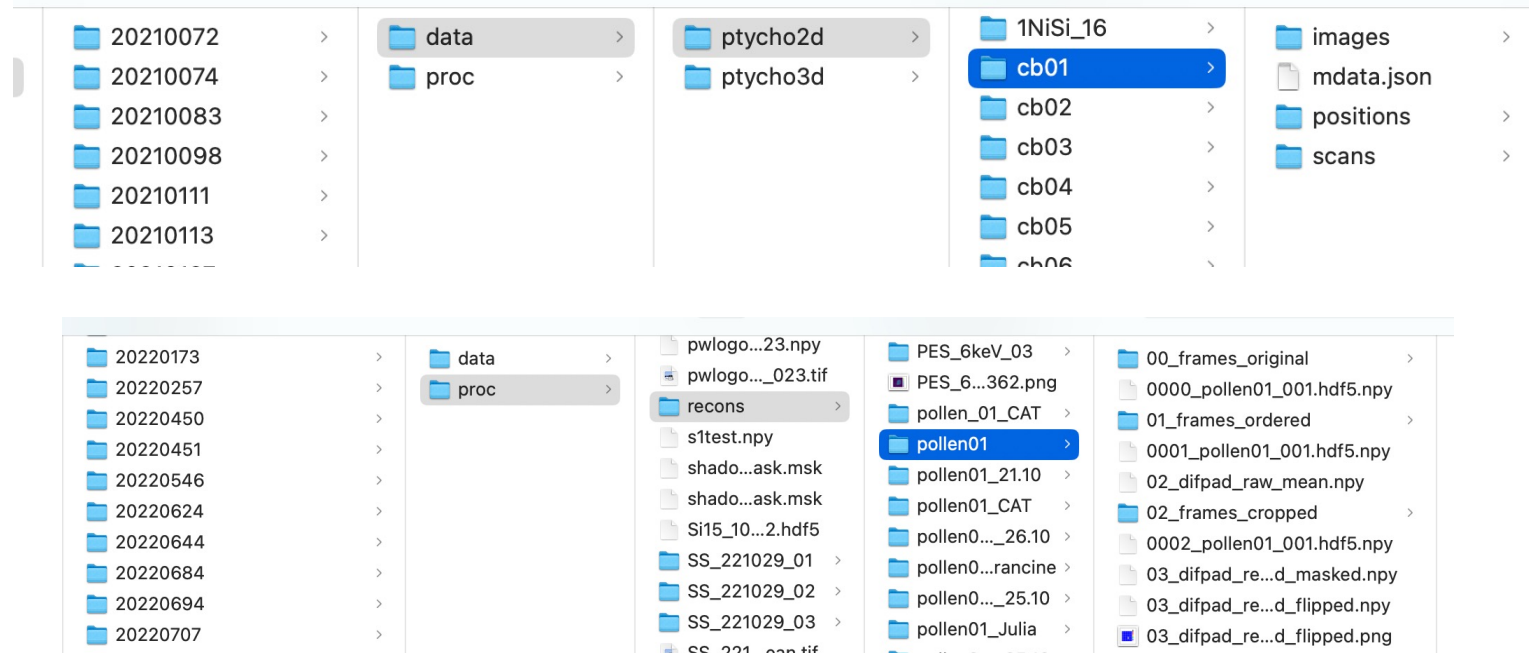
- High-level pre and post processing (Python)
- Current algorithms (CUDA):
  - RAAR
  - Alternating Projections + momentum
- Upcoming (Python + CUDA):
  - mPIE
  - Probe Decomposition
  - Position Correction
  - Plane Wave CDI:
    - ER, HIO, RAAR
- Tools from the community for benchmarking
  - PyNX
  - PtyPy
  - ...
- On the way to open science...





# Ptycho-tomo Pipeline

- Input and output data saved using predefined standard:
  - images
  - positions
  - scans
  - metadata
- Tomography: intermediate sinograms saved at each step
- Fast to adjust and optimize parameters





# Jupyter Interface for Ptychography

## Local vs Cluster

Machine ☐ Local ☒ Cluster

Insert # of GPUs to use:  1

Insert # of CPUs to use:  32

Insert machine queue name:

Job ID number

**Inputs**

Mask Find Center Probe Propagation Crop and Unwrap Reconstruction

**Data Selection**

Proposal Path

Data Folders

Projections

**Restoration**

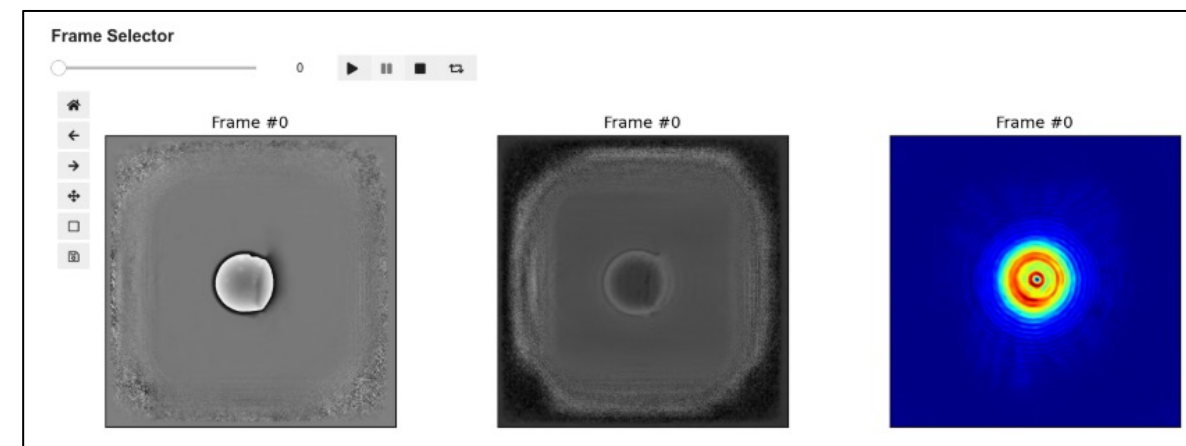
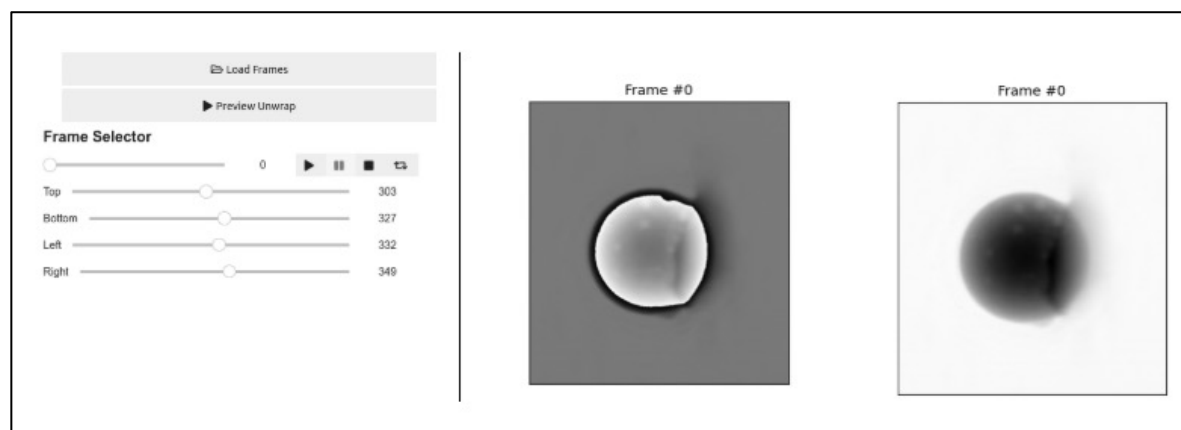
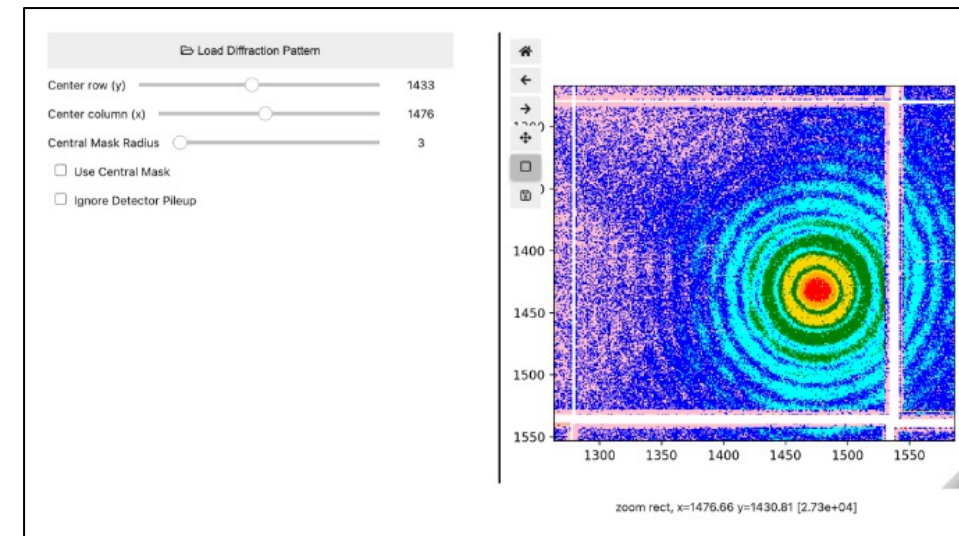
Center row (y)  1433

Center column (x)  1476

Diameter (pixels)  1280

Suppress pixels from chip border  5

Save or Load ☒ Save Diffraction Pattern ☐ Load Diffraction Pattern





# Jupyter for Ptycho-tomography

Contrast ☐ Absorption ☒ Phase Machine ☒ Local ☐ Cluster # of CPUs: 32 # of GPUs: 1 Machine Queue cat-proc

Steps to perform on cluster: ☐ Select and Sort ☐ Cropping ☐ Phase Unwrap ☐ Frame Equalizer ☐ Wiggle ☐ Tomography ☐ Equalize Tomo

Save inputs Start Delete temporary files

Select and Sort Cropping Phase Unwrap Frame Equalizer Wiggle Tomography

ibira Datapath (str) /ibira/Infs/beamlines/caterete/proposals/20210160/data/ptycho3d/

ibira Datafolders (list) ['glass21','glass22','glass23','glass24','glass25']

Ptycho sinogram path (str) /ibira/Infs/beamlines/caterete/proposals/20210160/proc/recons/glass21/glass21\_object.npy

Load Data

Frame Selector (Time) 109 Time/frame [ms] 300

Sort frames

Frame Selector (Angle) 109 Time/frame [ms] 300

Frame #109

Frame #109

Contrast ☐ Absorption ☒ Phase Machine ☒ Local ☐ Cluster # of CPUs: 72 # of GPUs: 1 Machine Queue cat-proc

Steps to perform on cluster: ☐ Select and Sort ☐ Cropping ☐ Phase Unwrap ☐ Frame Equalizer ☐ Wiggle ☐ Tomography ☐ Equalize Tomo

Save inputs Start Delete temporary files

Select and Sort Cropping Phase Unwrap Frame Equalizer Wiggle Tomography

Sinogram to import: ☐ cropped ☐ unwrapped ☒ equalized

Load sinogram

Remove Bad Frames

Bad Frames [145, 180]

Angle Step 0

Simulate Projection

Project Angles

Reference Frame 59 Time/frame [ms] 300

# of CPUs: 72

Plot direction: ☐ X ☒ Y ☐ Z

Perform Wiggle

Sinogram Slice 304

Pre-wiggle sinogram

Wiggled sinogram

Pre-wiggle sample

Load cropped frames

Bad frames [167, 186, 201]

Remove Bad Frames

Perform Unwrap

Frame Selector 109 Time/frame [ms] 300

Unwrap Iterations 0

☐ Non-negativity

☐ Gradient

Frame #109

Frame #109

☐ Apply Regularization

Regularization Parameter 0.001

Iterations 20

Plot direction: ☐ X ☐ Y ☒ Z

Load recon slices Load: ☐ Original ☒ Equalized

Slice # 279

Remove Outliers 0

Bkg Offset [y0,yd,xl,xr] []

Mask [y0,yd,xl,xr] []

Value threshold 20

Histogram Maximum 2000

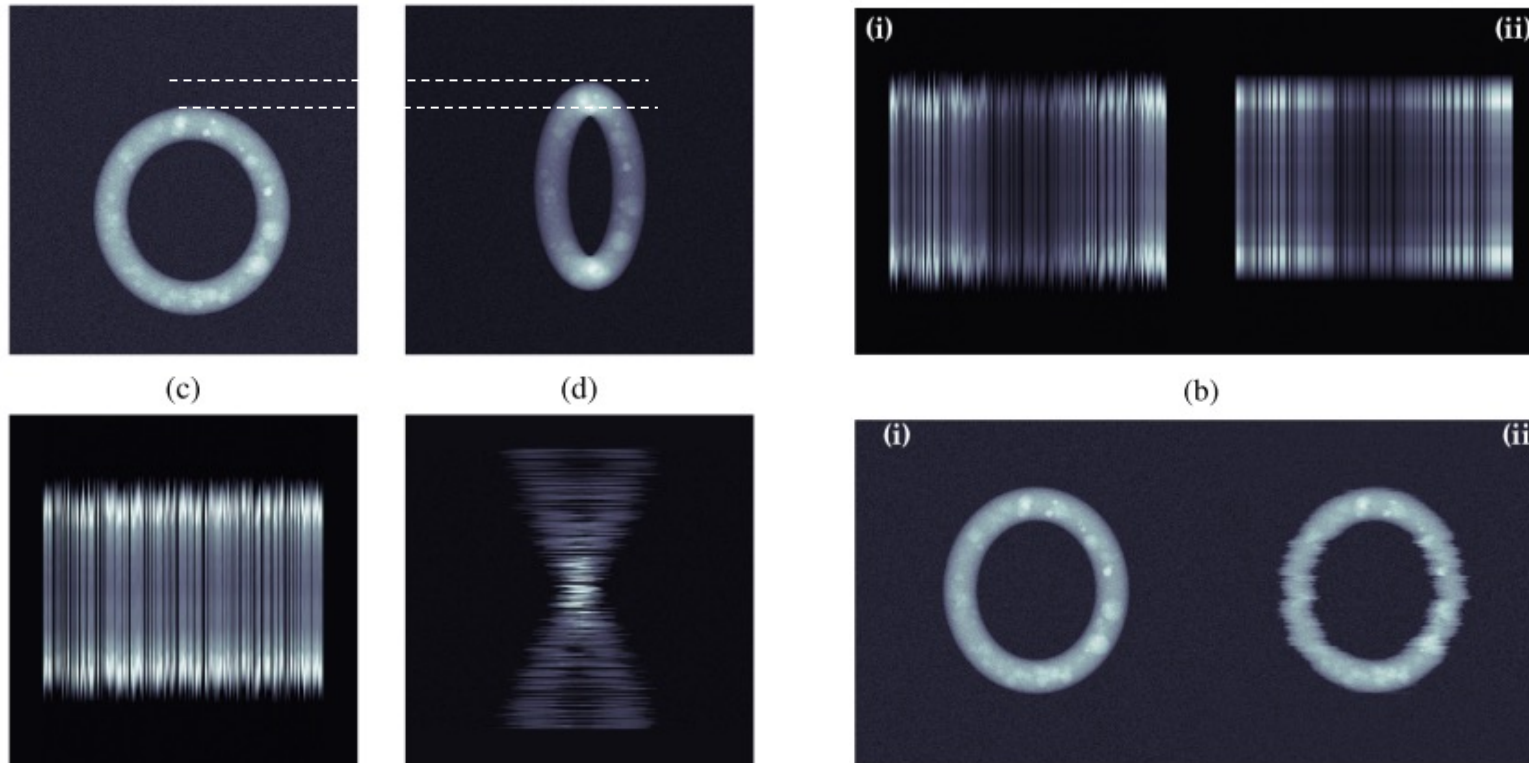
Equalize Reconstruction

Tomo slice

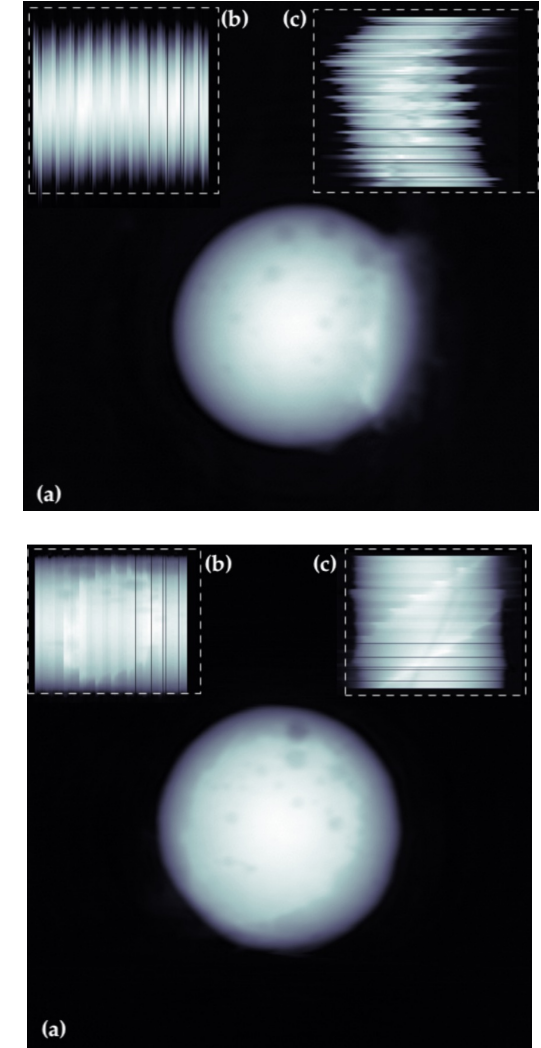
Tomo projection



# Frame alignment: “wobble”



Ptychography @ Cateretê



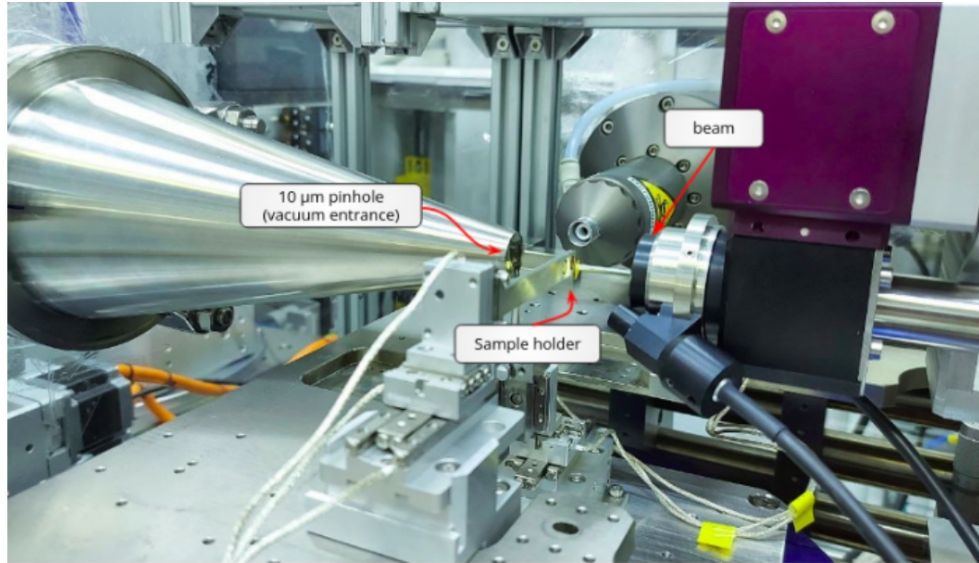
Ludwig-Helgason consistency conditions:

$$\frac{\int dx dy y F(\theta, y - h, x)}{\int dx dy F(\theta, y - h, x)} = \frac{\int dx dy y F(\theta_{\text{REF}}, y, x)}{\int dx dy F(\theta_{\text{REF}}, y, x)}$$

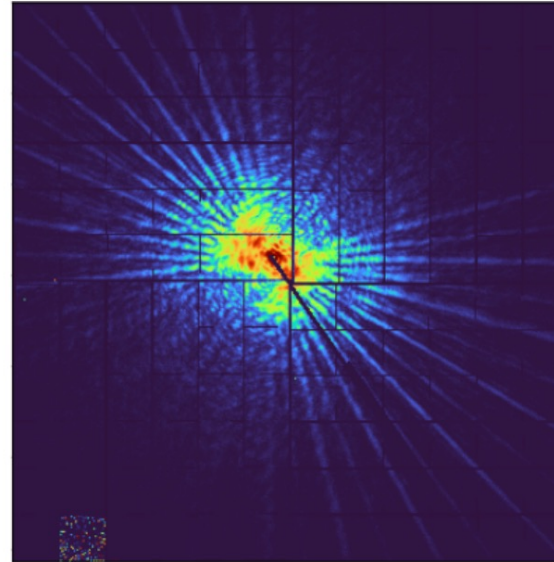


# CATERETÊ - Ptychography

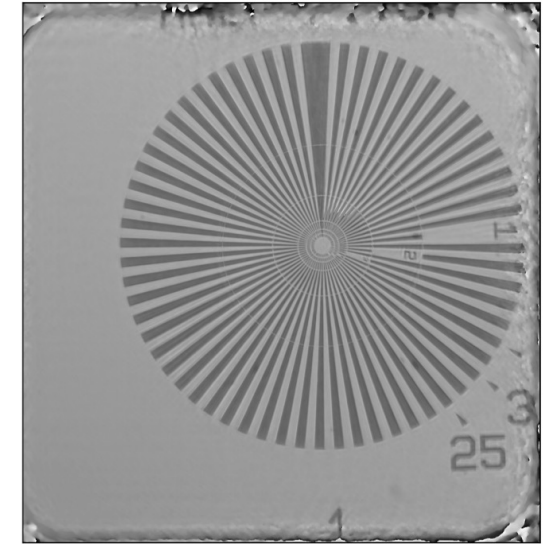
- Step-scan tele-ptychography, pink-beam



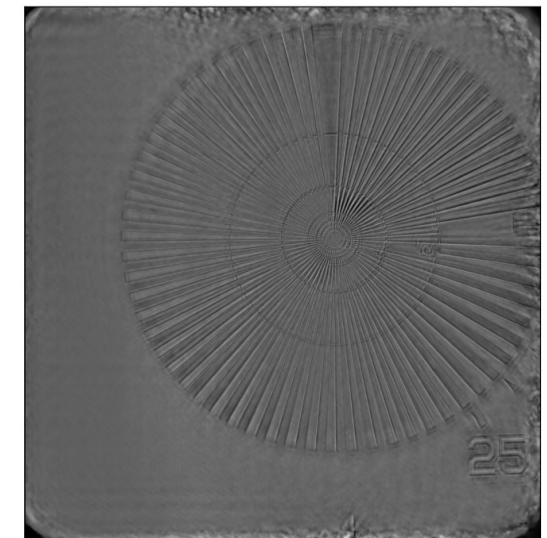
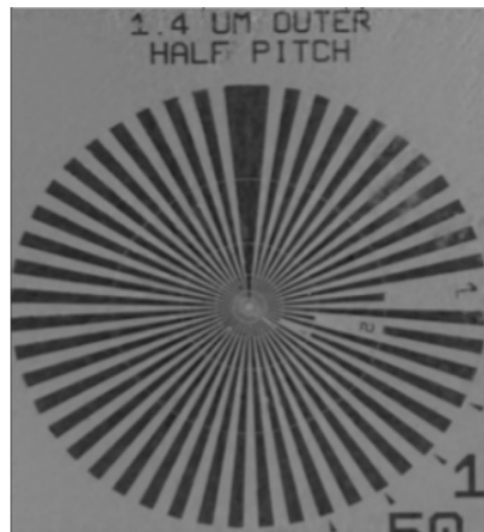
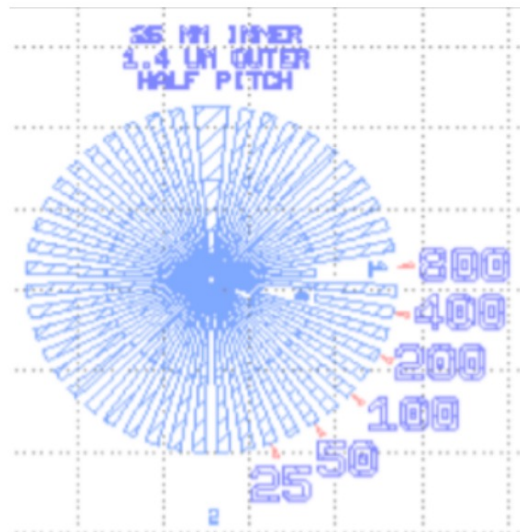
[www.lnls.cnpem.br/sirius-updates](http://www.lnls.cnpem.br/sirius-updates)



- Monochromatic beam



Phase

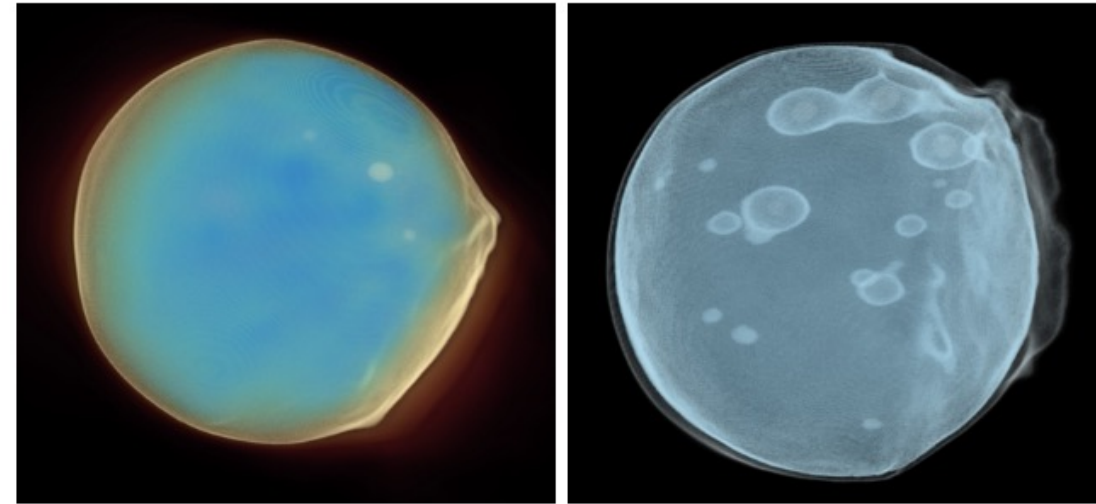


Absorp.



# 3D Visualization

- NVIDIA Index rendering
  - Many shader options
  - Fast rendering powered by NVIDIA
  - Customizable shaders for specific materials



Click "Watch Now" to login or join the NVIDIA Developer Program.

**WATCH NOW**

## High-Throughput 3D Image Reconstruction, Visualization, and Segmentation of Large-Scale Data at the Sirius Synchrotron Light Source

**Thiago Vallin Spina, Brazilian Synchrotron Light Laboratory / CNPEM**

### GTC 2020

We'll present highly efficient tools for large-scale 3D image reconstruction, visualization, and segmentation being developed for the Sirius synchrotron light source. Sirius will be the second fourth-generation synchrotron in the world, and will acquire 3D/4D images with resolution up to <50 nm using hard X-rays. With NVIDIA, we're creating integrated pipelines to reconstruct 3D images from modalities such as coherent-diffraction imaging and transmission tomography, visualize the data in streaming mode, and segment the images to provide almost real-time feedback. We rely on multi-GPU/node CUDA programming and machine/deep learning-optimized inference to address the issues, given that each 3D image may be larger than 100 GB and may be acquired down to 1s, resulting in around 50 TB of data of a wide variety of samples (for example, biological and geological) expected to be produced every day.

<https://developer.nvidia.com/gtc/2020/video/s21278-vid>

# CATERETÊ – Ptycho-tomography

MINISTRY OF  
SCIENCE TECHNOLOGY  
AND INNOVATION

BRAZILIAN GOVERNMENT  
**BRASIL**  
UNITING AND REBUILDING

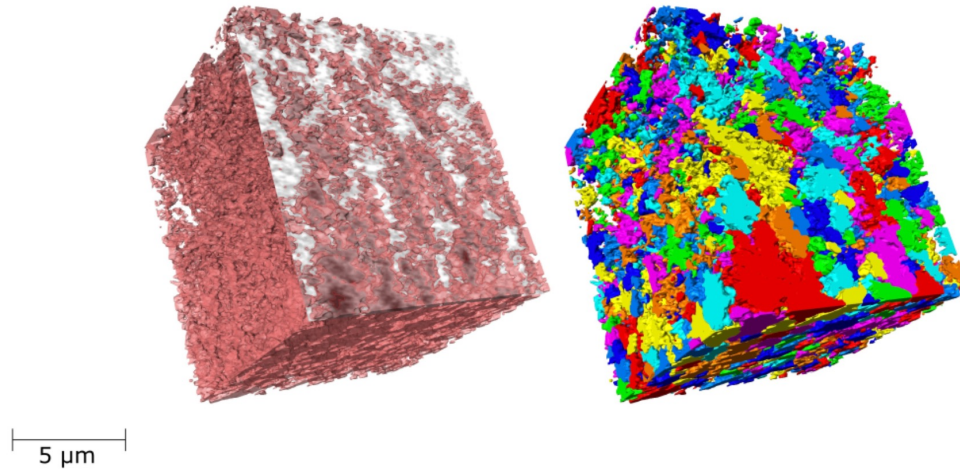


**CNPq**

Dean



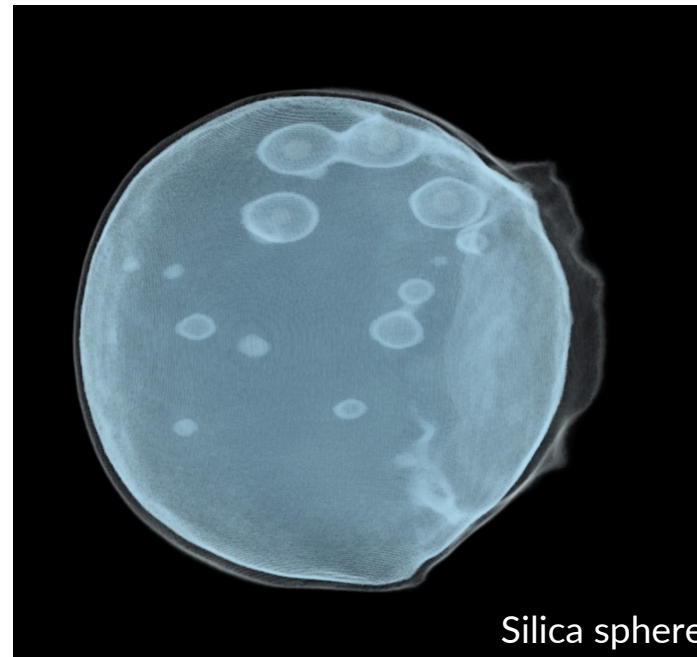
Talita



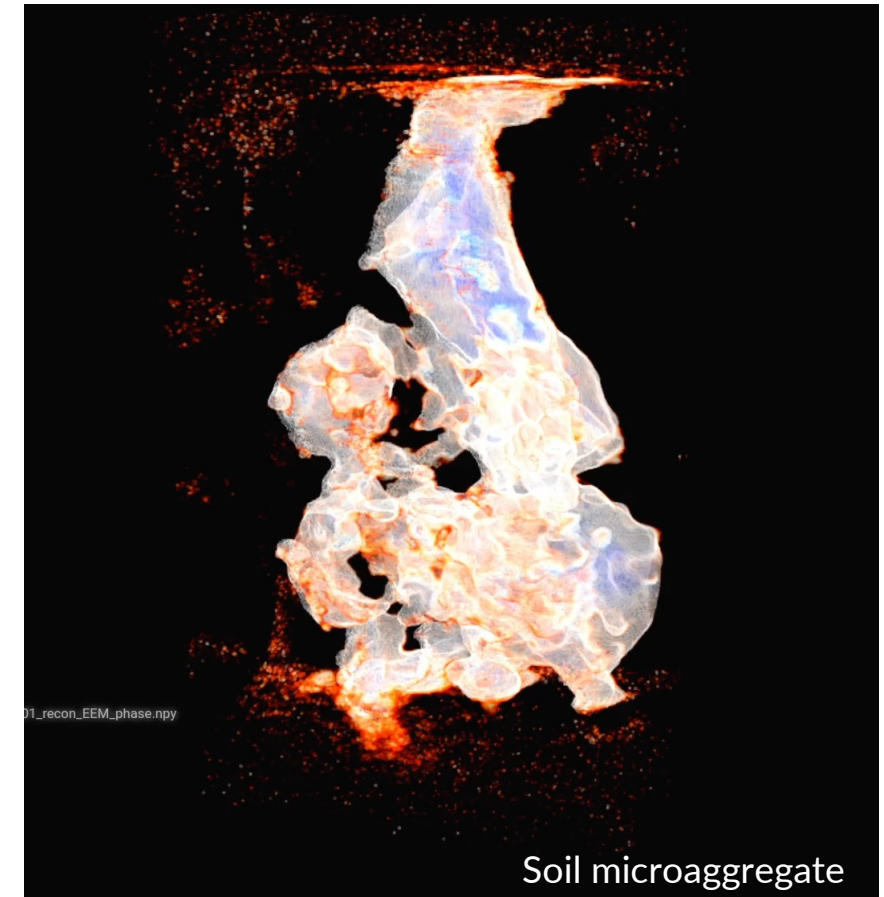
5  $\mu$ m



Grain of Pollen



Silica sphere



Soil microaggregate



Carla



CAR

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BA

CNPem

MINISTRY OF  
SCIENCE TECHNOLOGY  
AND INNOVATION

BRAZILIAN GOVERNMENT  
BRASIL  
UNITING AND REBUILDING



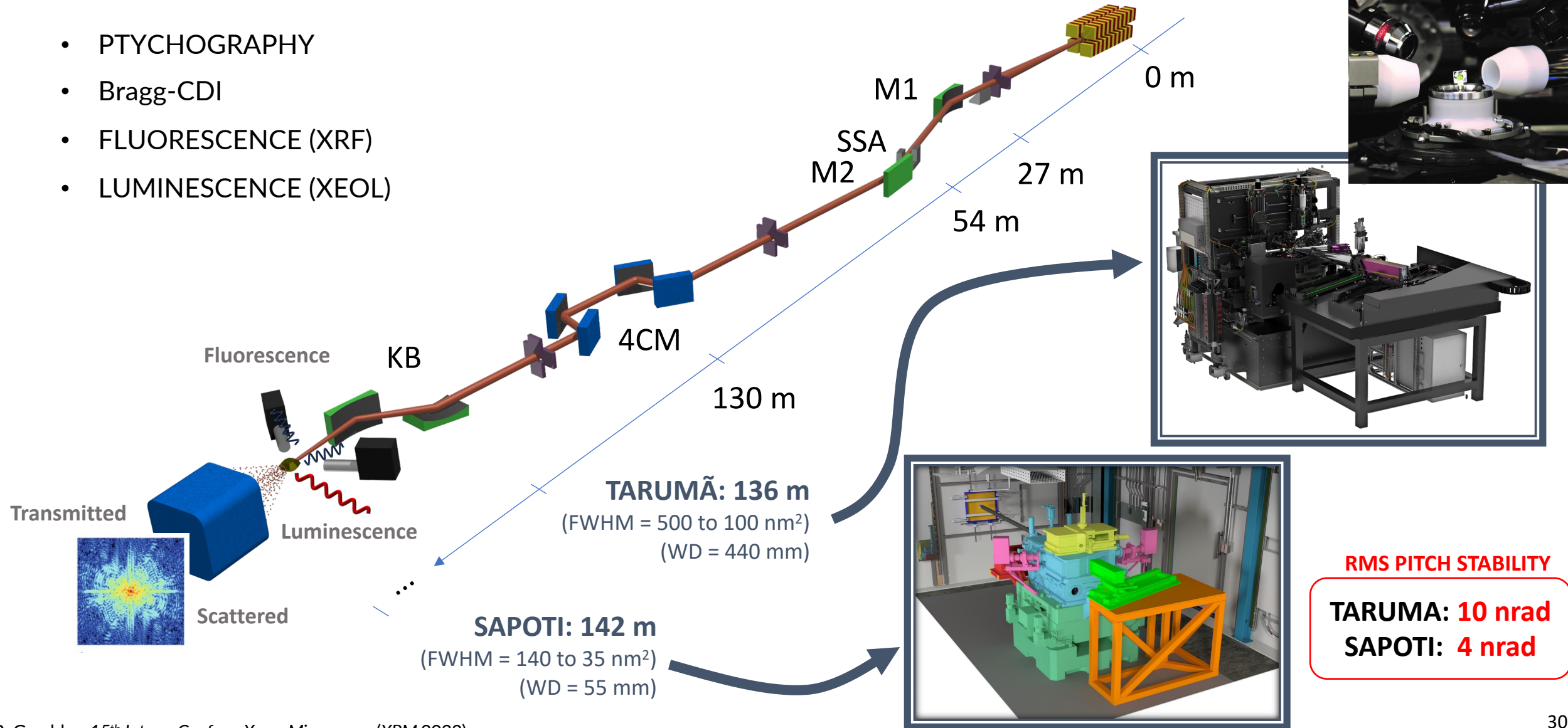
CNPem

## X-ray Nanoscopy



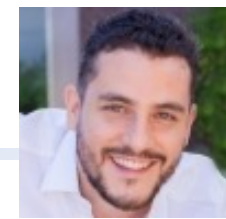
# CARNAÚBA beamline

- PTYCHOGRAPHY
- Bragg-CDI
- FLUORESCENCE (XRF)
- LUMINESCENCE (XEOL)

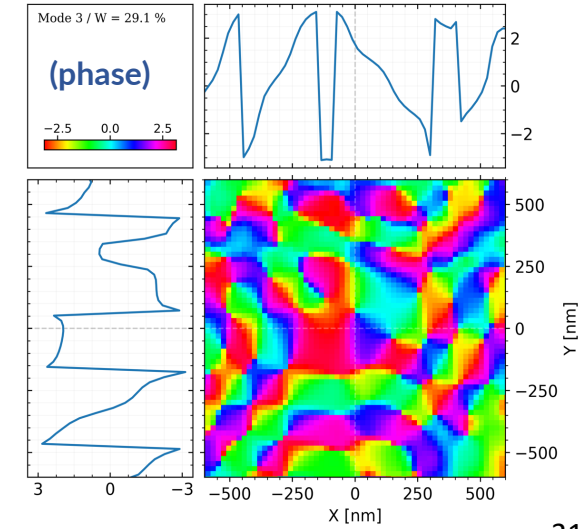
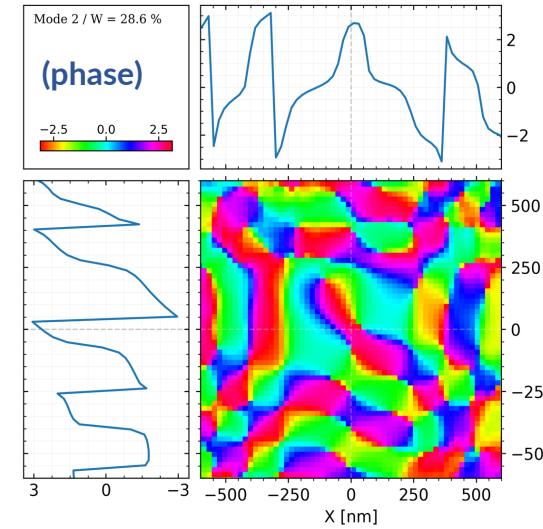
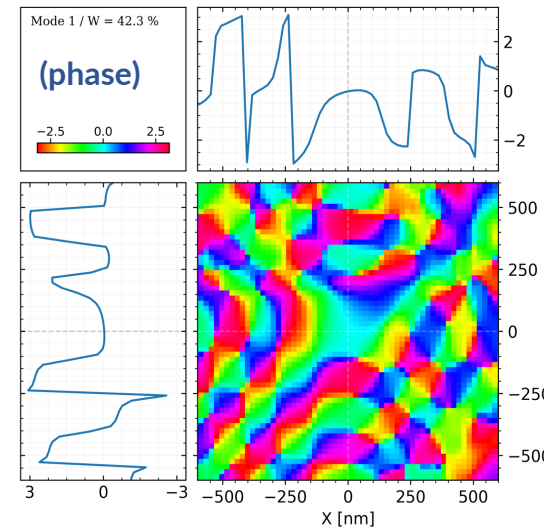
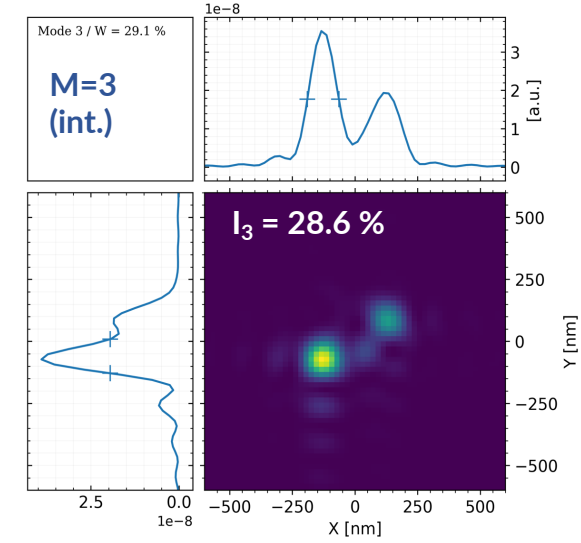
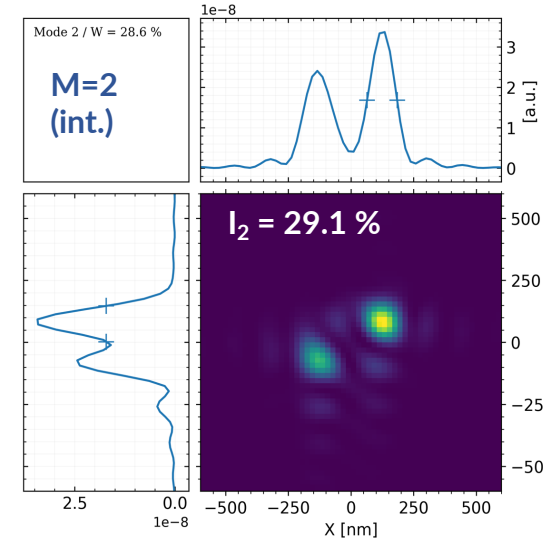
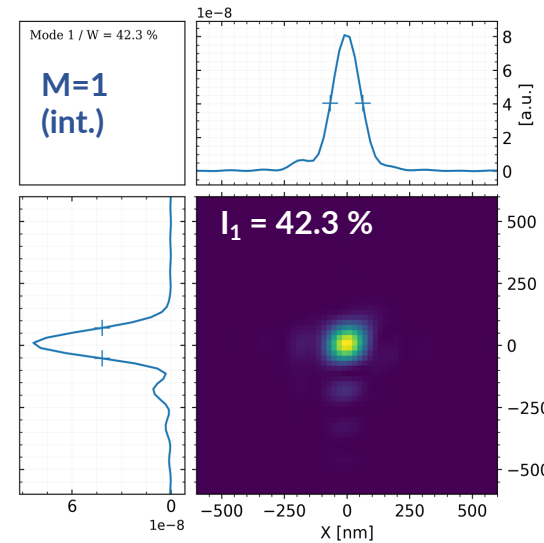
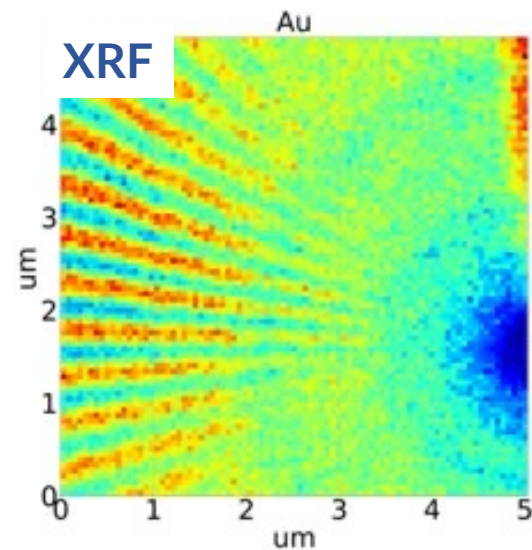
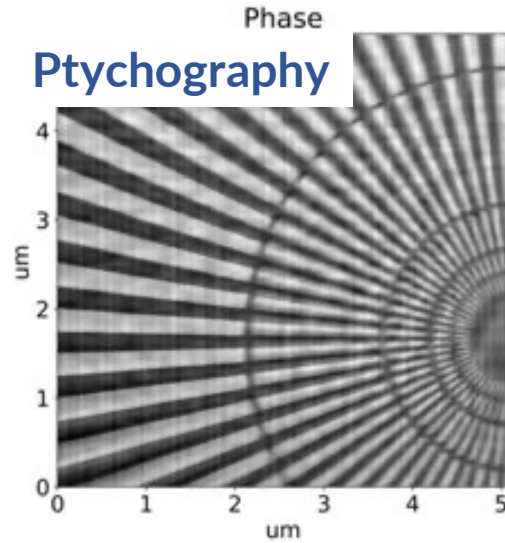




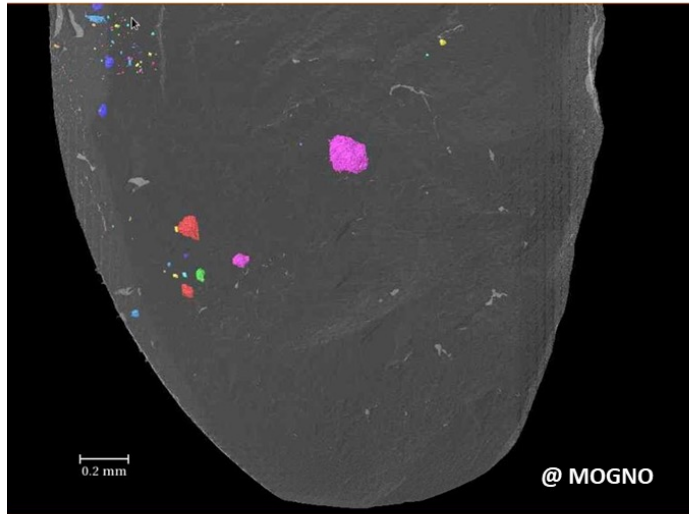
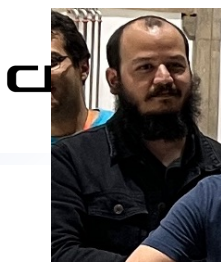
# CARNAÚBA: Ptychography



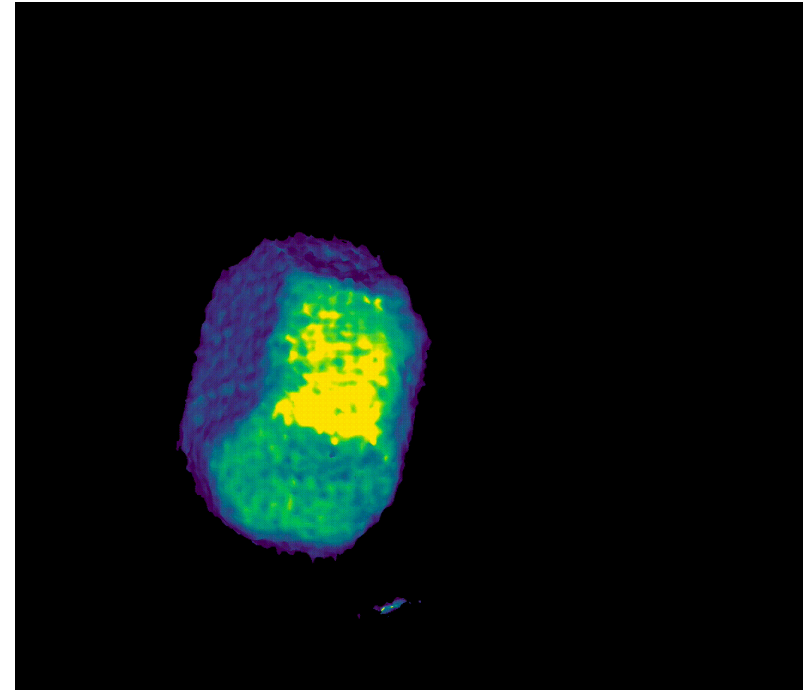
## Incoherent modes



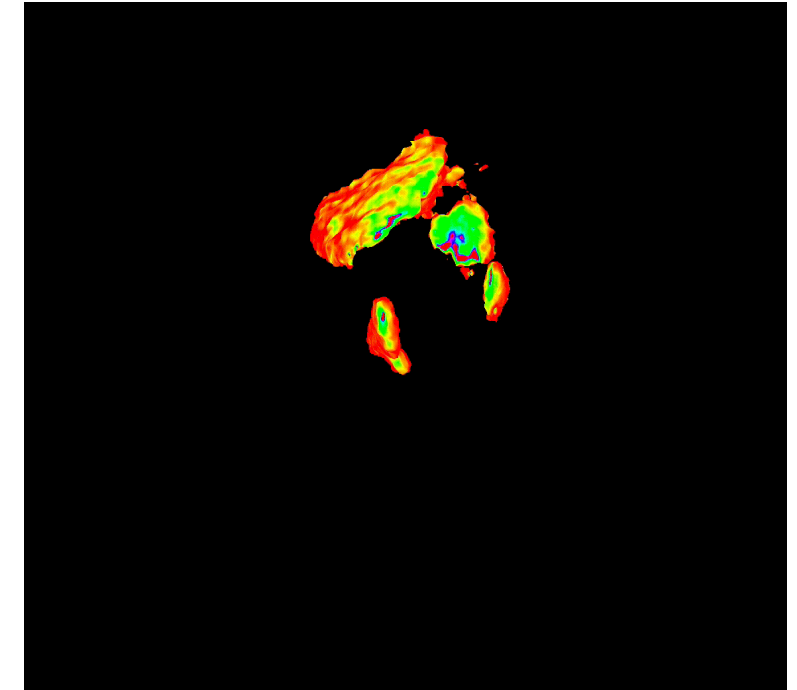
# CARNAÚBA: Fluorescence



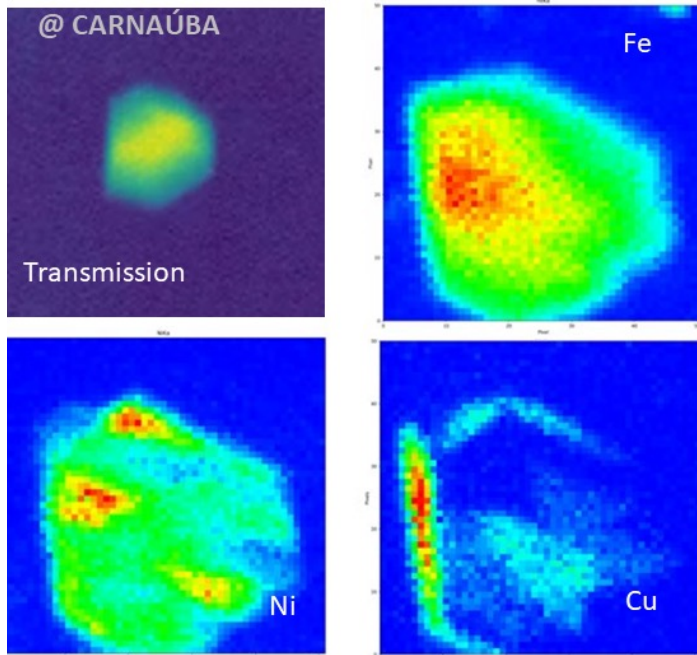
→ Tomography of a diamond sample with solid mineral inclusions



Transmission tomography



Fluorescence tomography  
(Cu layer)

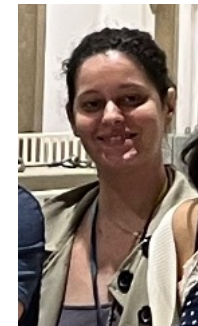
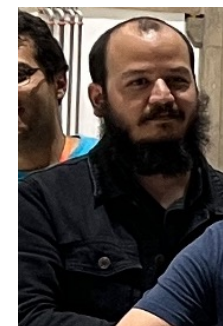
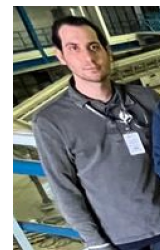
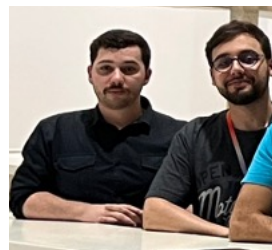


→ Fluorescence mapping of one solid mineral inclusion

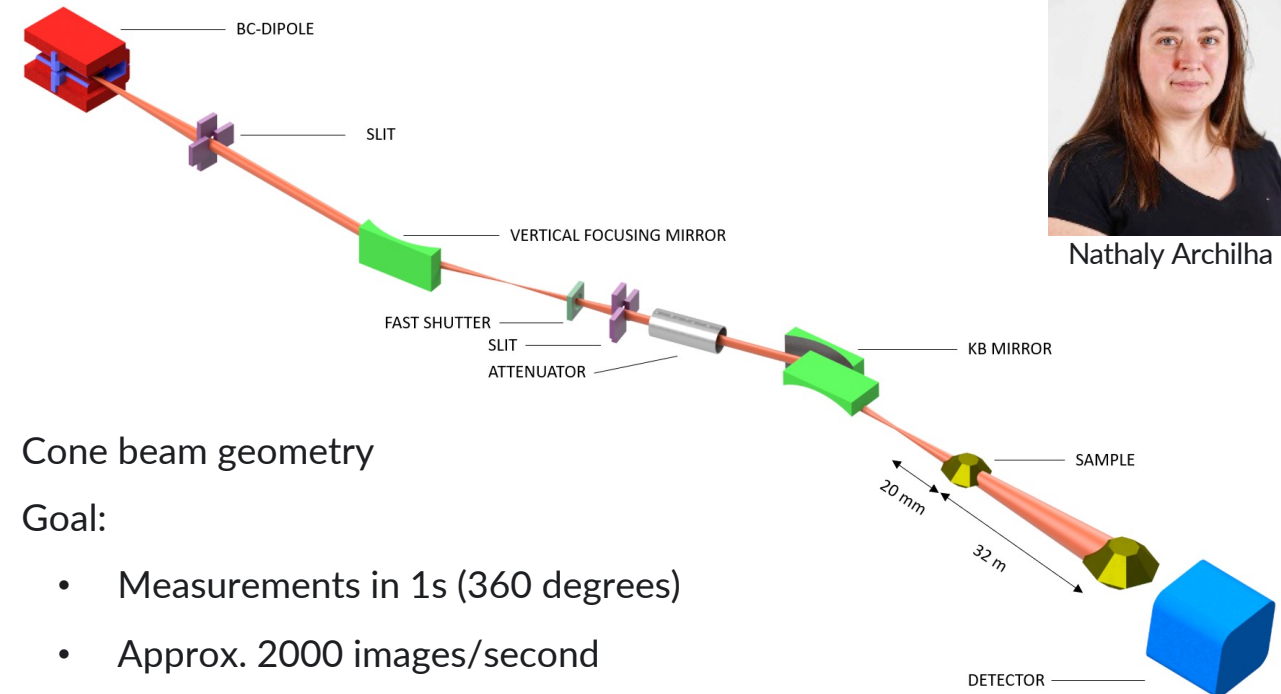
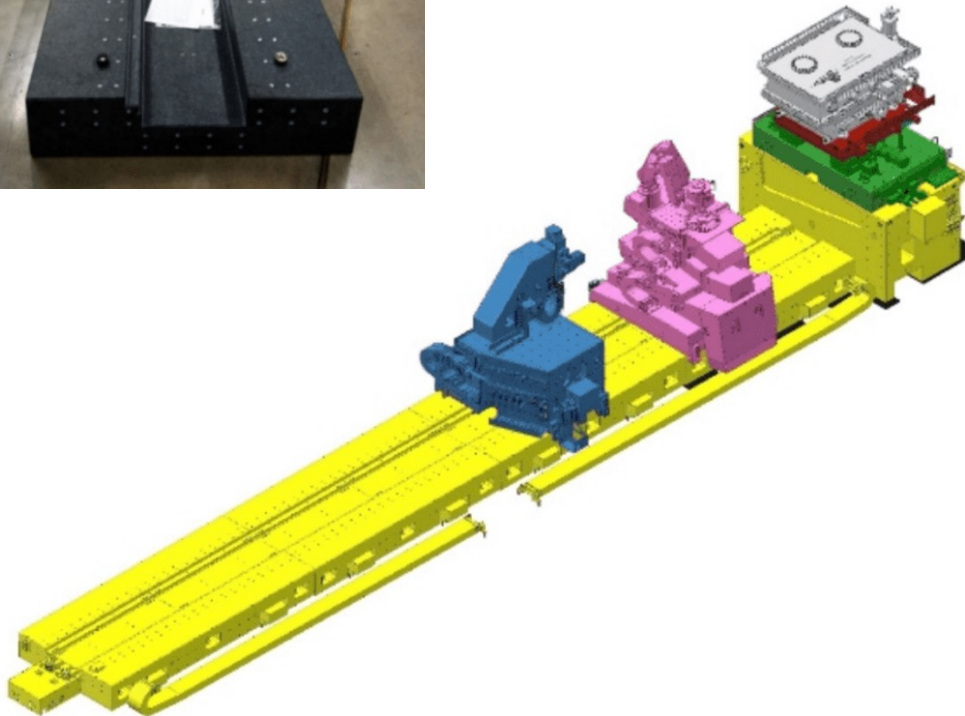




## X-ray Micro and Nanotomography



# MOGNO beamline



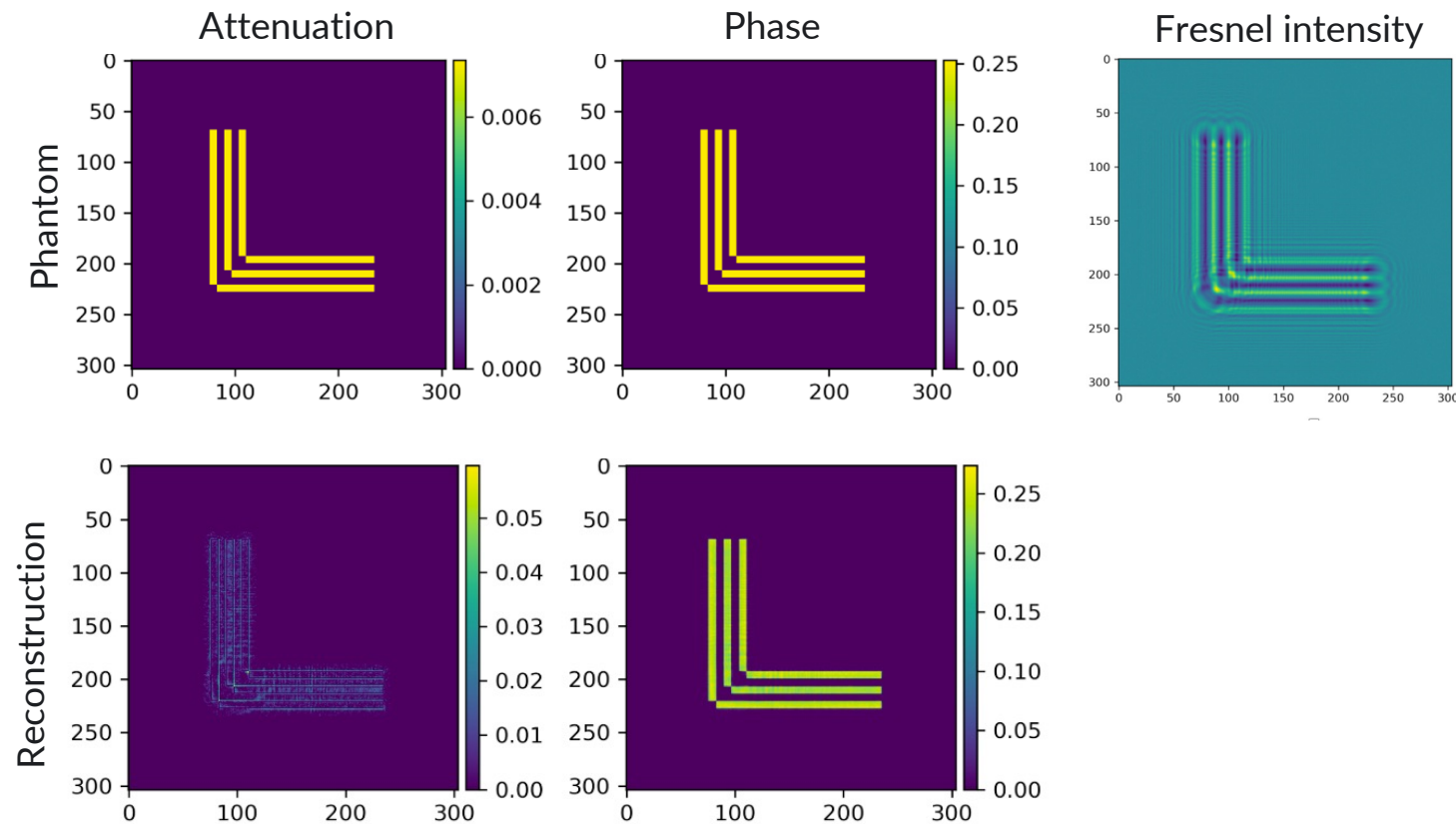
Nathaly Archilha

- Cone beam geometry
- Goal:
  - Measurements in 1s (360 degrees)
  - Approx. 2000 images/second
  - 150 nm target resolution @ nano-station
  - Reconstruction in quasi-real time (analytical)
- $N \times 2048^2 \rightarrow 35$  GBs (PCO edge 4.2 CLHS)
- $N \times 1536^2 \rightarrow 20$  GBs (PIMEGA 135D)
- 4D tomography (X, Y, Z, time):
  - in vivo samples
  - fluid injection in porous media

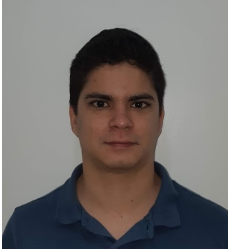
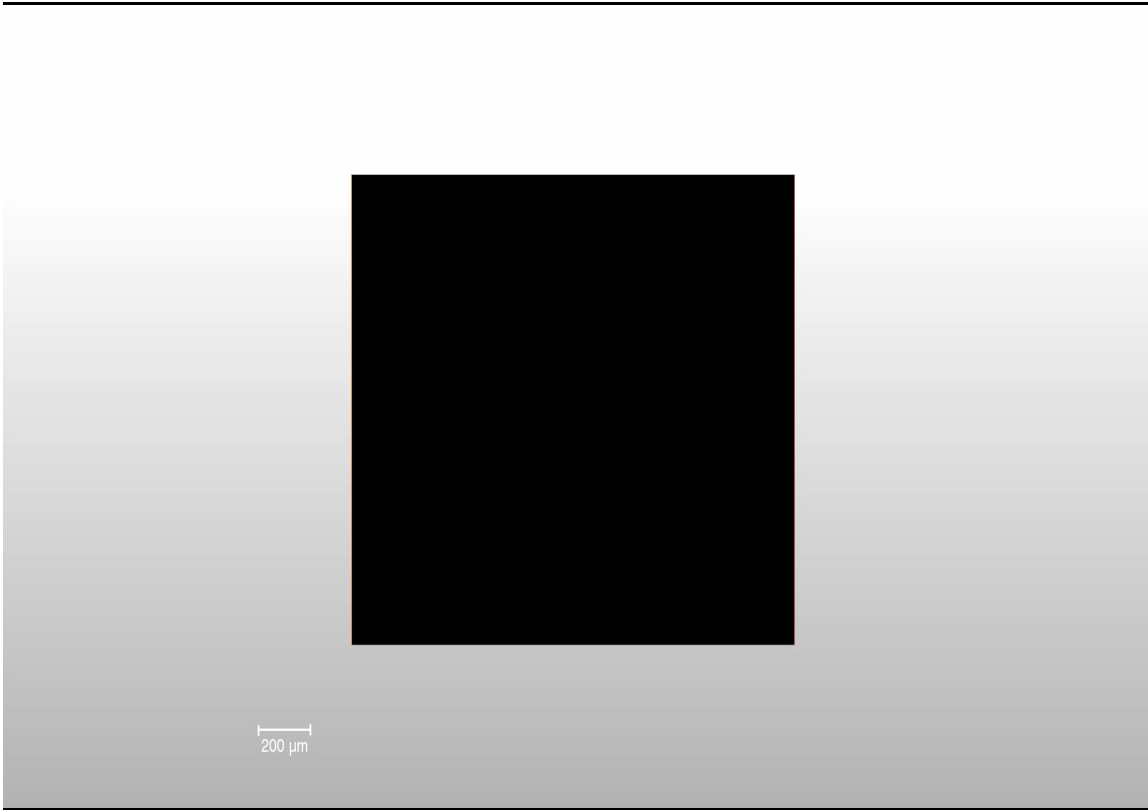
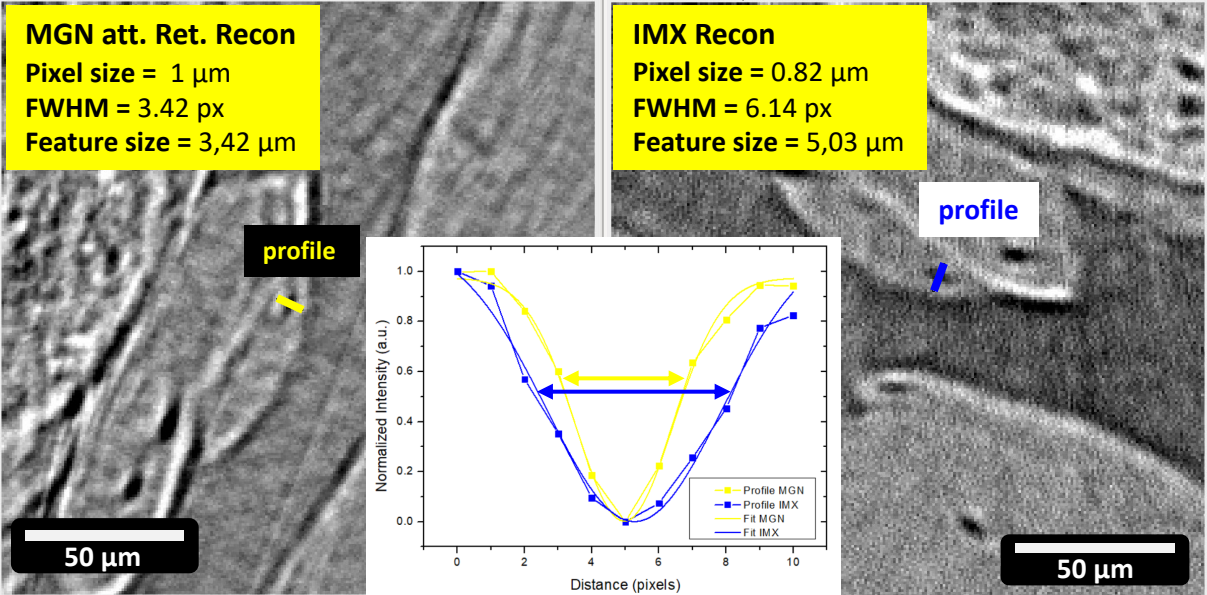
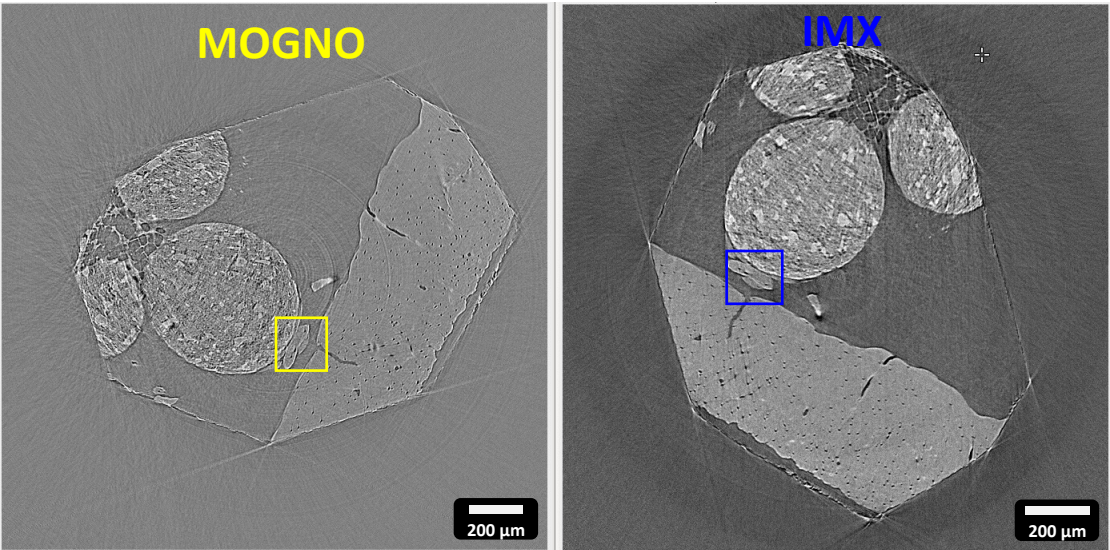


# Phase Retrieval

- Iterative Regularized Gauss-Newton Method for Phase Retrieval
  - "Regularized newton methods for x-ray phase contrast and general imaging problems," Opt. Express, vol. 24, no. 6, pp. 6490–6506, 2016
- PCO (planar detector chips); future measurements using Pimega135D



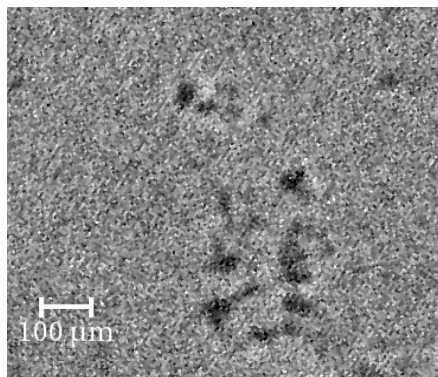
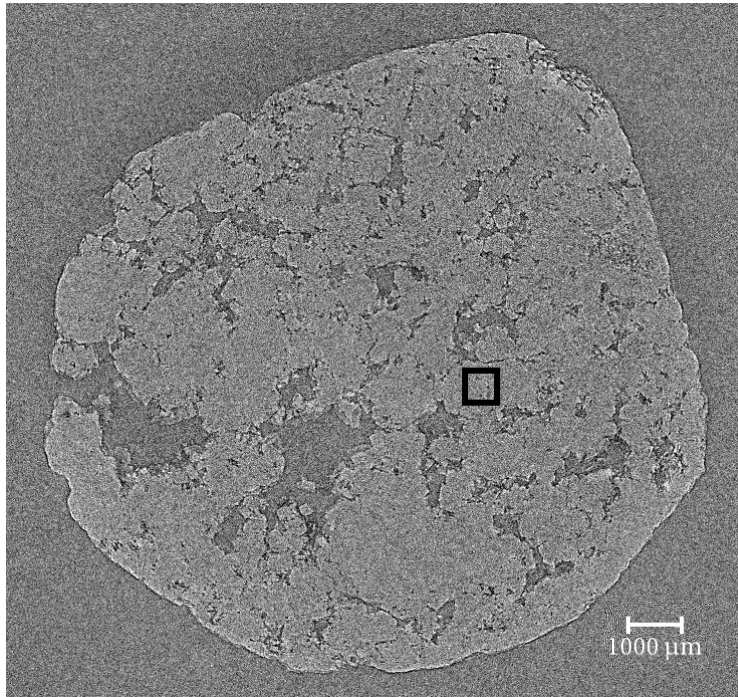
# Nano-hydroxyapatite-based microspheres implanted in rat tibia defect as a bone graft substitute



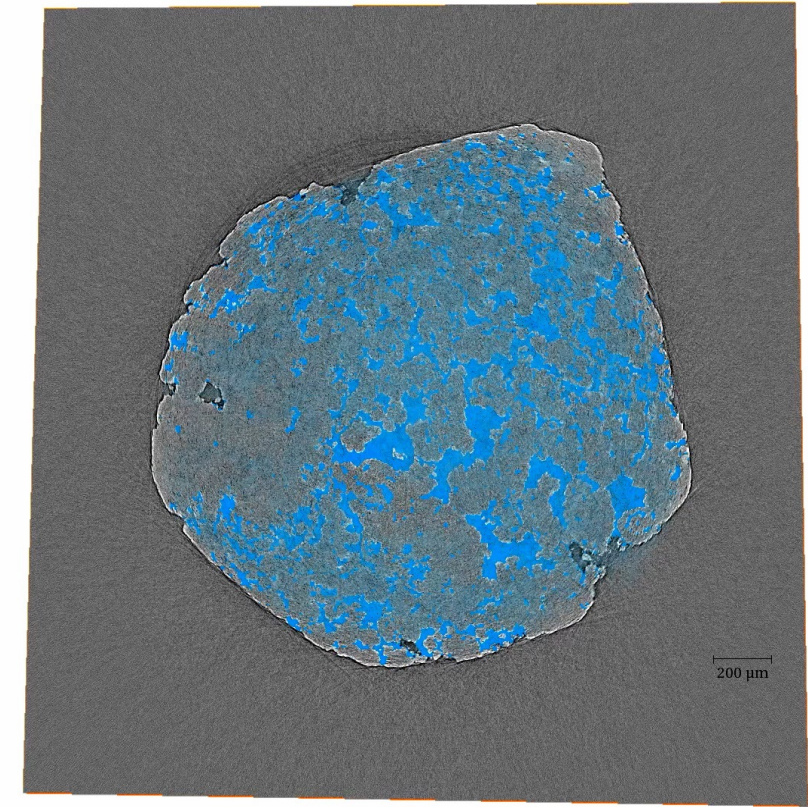
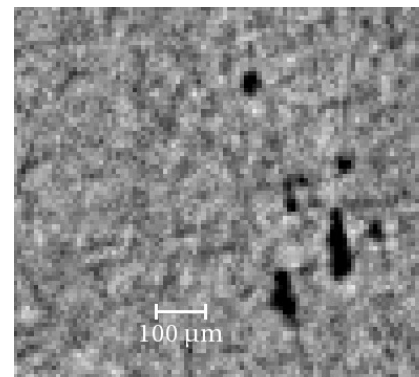
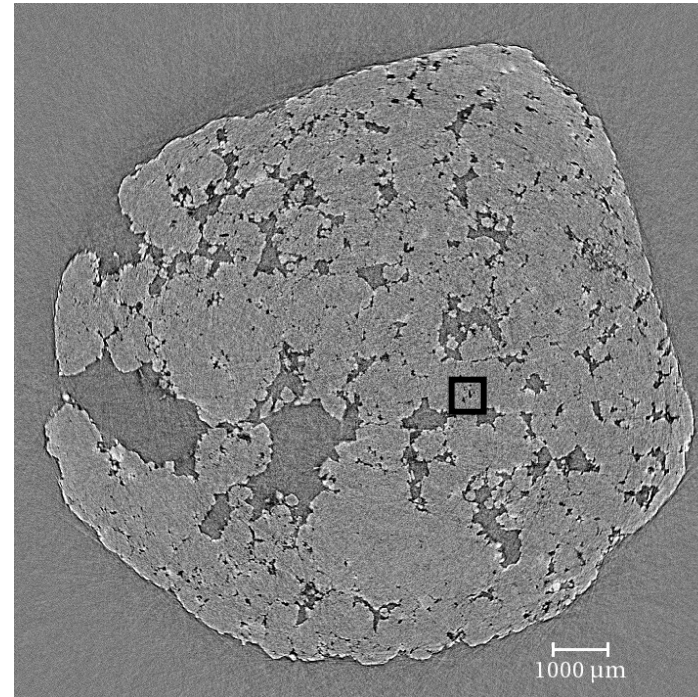


# Pre-Salt limestone

Feb/2021 – Mogno A

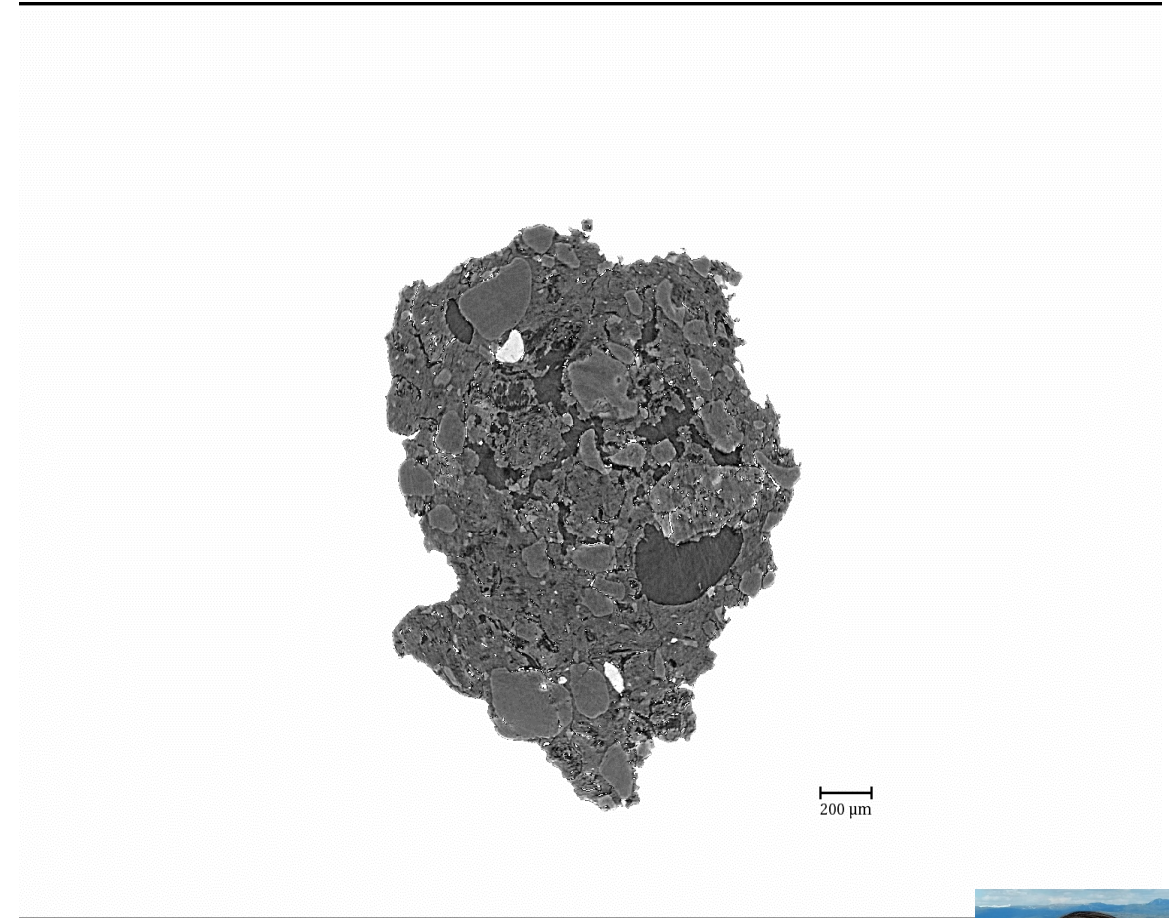
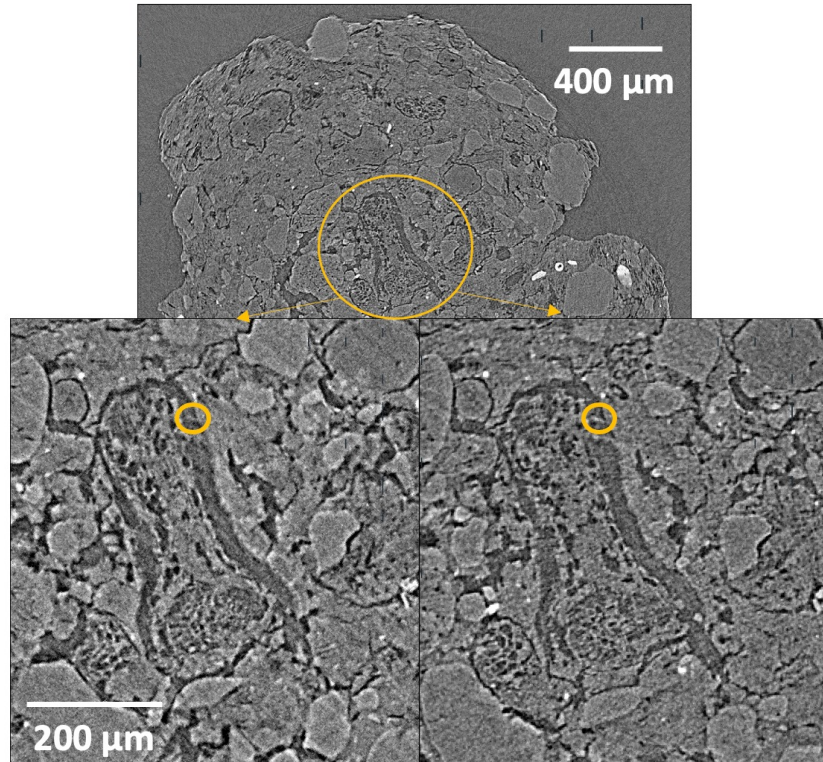


Oct/2022 - Mogno

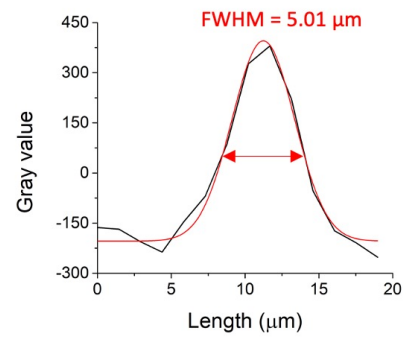
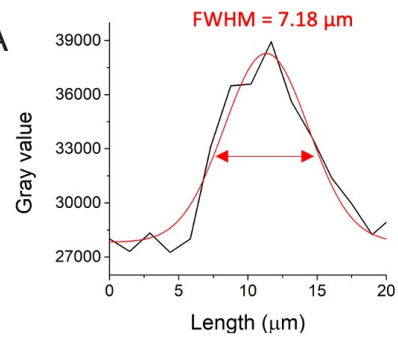




# Soil Aggregate



Mogno A

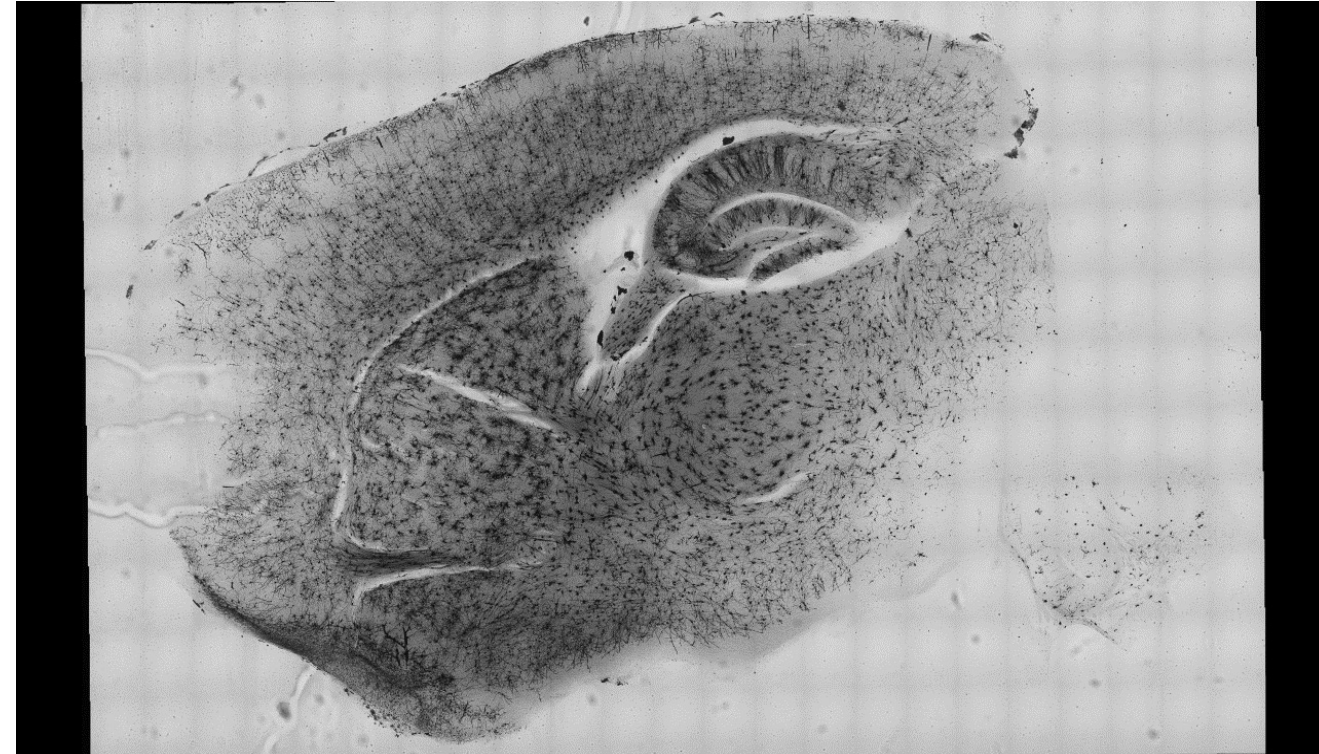
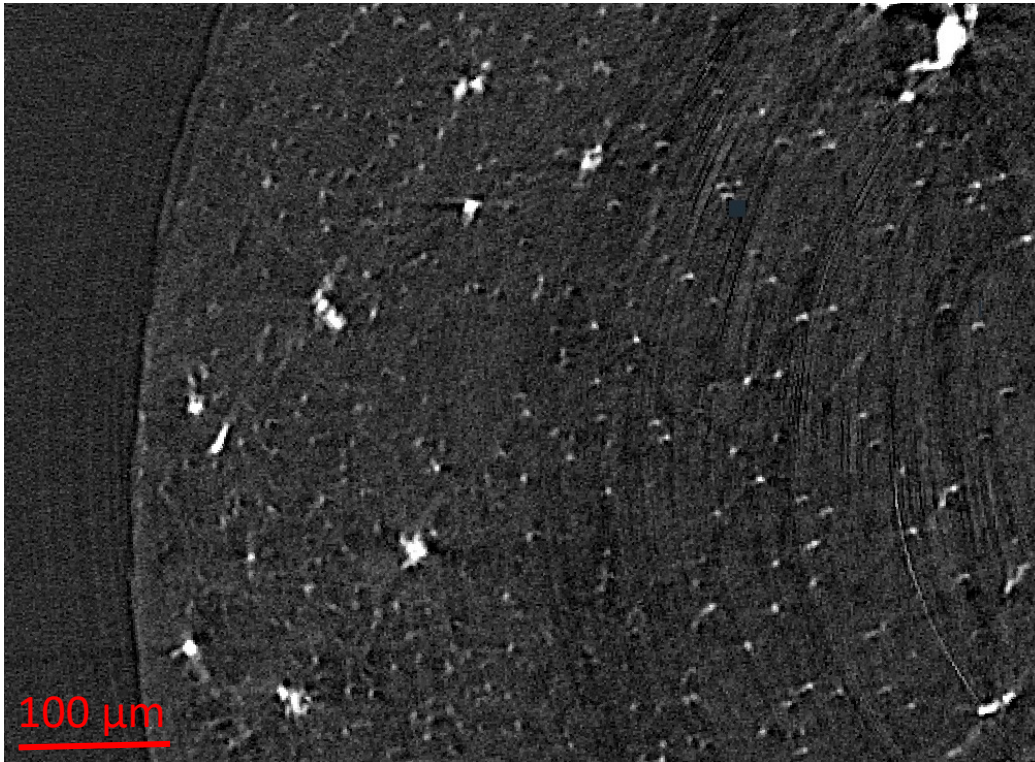


Mogno

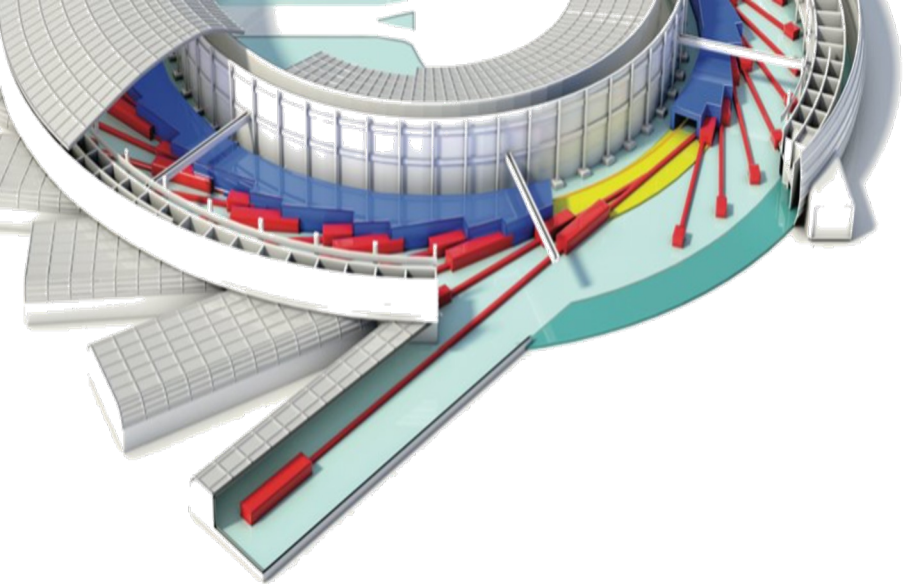




# Golgi-cox stained Neurons

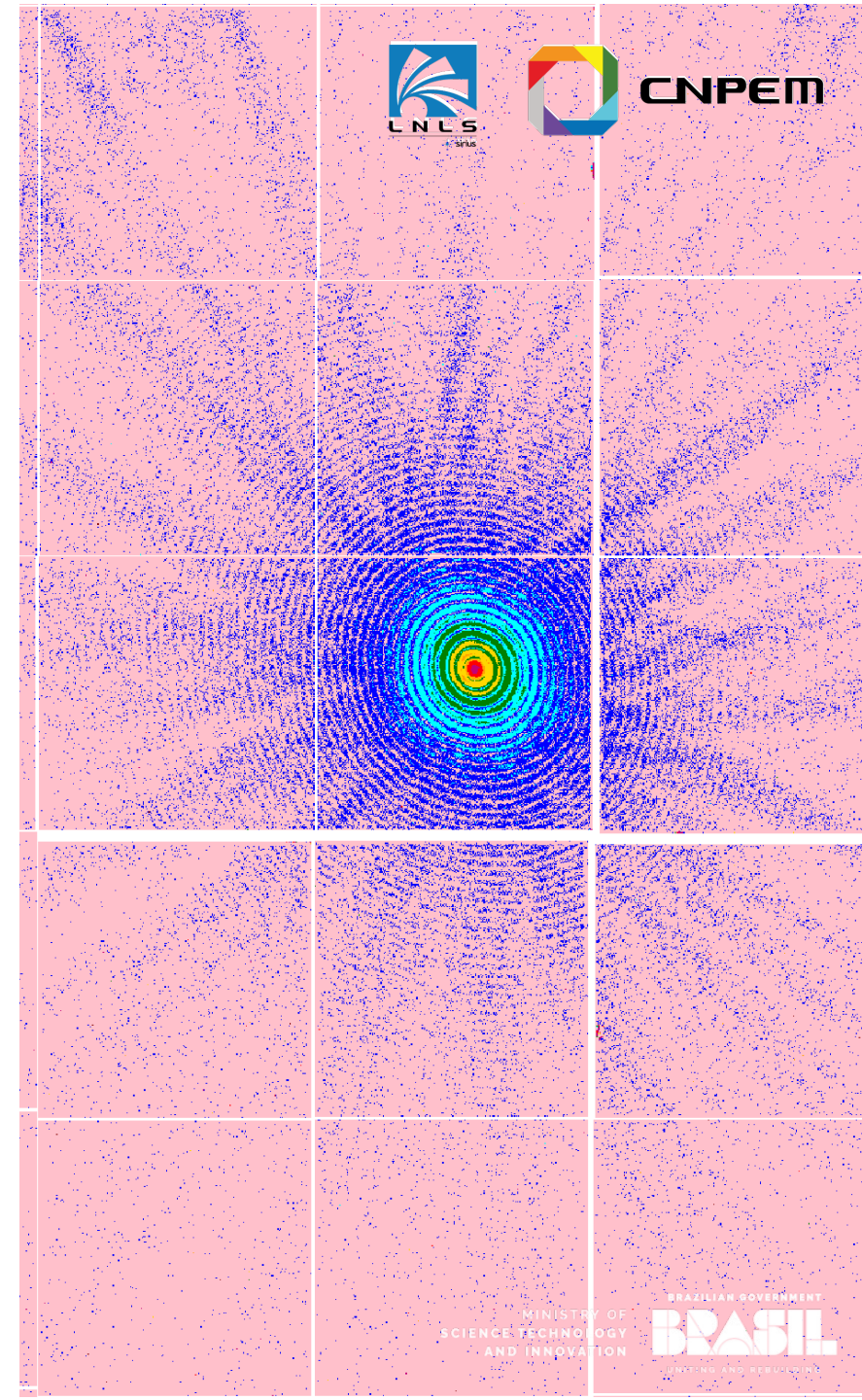






## Conclusion

- Scientific Computing at Sirius
  - has been steadily growing
  - target towards excellency in inverse problems
  - R&D + user support
  - Up to 2023, focus on imaging problems
    - ... but more fields to come in the future!
  - Preliminary results seem promising!
  - Margin for much improvement; numerous challenges ahead
- Looking forward to discuss and collaborate!



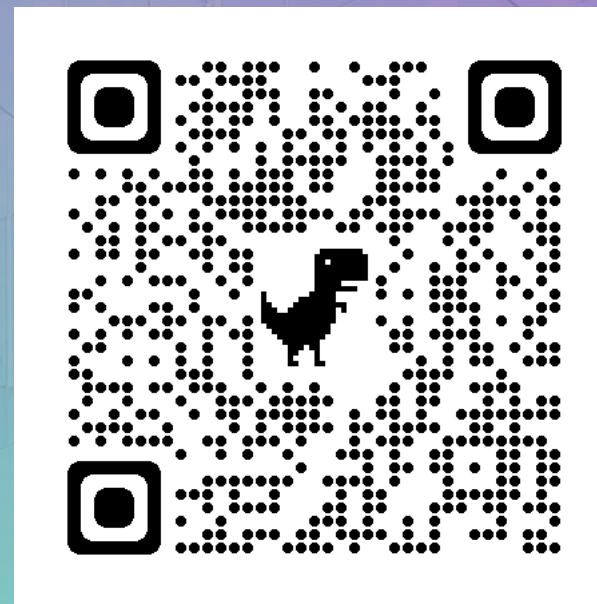


# Thank you!

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